



AMERICAN METEOROLOGICAL SOCIETY

Journal of Physical Oceanography

EARLY ONLINE RELEASE

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The DOI for this manuscript is doi: 10.1175/JPO-D-17-0192.1

The final published version of this manuscript will replace the preliminary version at the above DOI once it is available.

If you would like to cite this EOR in a separate work, please use the following full citation:

Viglione, G., A. Thompson, M. Flexas, J. Sprintall, and S. Swart, 2018: Abrupt transitions in submesoscale structure in Southern Drake Passage: Glider observations and model results. *J. Phys. Oceanogr.* doi:10.1175/JPO-D-17-0192.1, in press.



Abrupt transitions in submesoscale structure in Southern Drake Passage:

Glider observations and model results

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ABSTRACT

12 Enhanced vertical velocities associated with submesoscale motions may
13 rapidly modify mixed layer depths and increase exchange between the mixed
14 layer and the ocean interior. These dynamics are of particular importance
15 in the Southern Ocean, where the ventilation of many density classes oc-
16 curs. Here we present results from an observational field program in southern
17 Drake Passage, a region preconditioned for submesoscale instability due to
18 its strong mesoscale eddy field, persistent fronts, strong down-front winds,
19 and weak vertical stratification. Two gliders sampled from December 2014
20 through March 2015 upstream and downstream of Shackleton Fracture Zone
21 (SFZ). The acquired time series of mixed layer depths and buoyancy gra-
22 dients enabled calculations of potential vorticity and classifications of sub-
23 mesoscale instabilities. The regions flanking the SFZ displayed remarkably
24 different characteristics despite similar surface forcing. Mixed layer depths
25 were nearly twice as deep and horizontal buoyancy gradients were larger
26 downstream of the SFZ. Upstream of the SFZ submesoscale variability was
27 confined to the edges of topographically-steered fronts, whereas downstream
28 these motions were more broadly distributed. Comparisons to a 1-D mixing
29 model demonstrate the role of submesoscale instabilities in generating mixed
30 layer variance. Numerical output from a submesoscale-resolving simulation
31 indicates that submesoscale instabilities are crucial for correctly reproducing
32 upper ocean stratification. These results show that bathymetry can play a
33 key role in generating dynamically-distinct submesoscale characteristics over
34 short spatial scales and that submesoscale motions can be locally active during
35 summer months.

36 **1. Introduction**

37 The Southern Ocean plays a key role in Earth's climate due to the ventilation of deep waters
38 and the subduction of newly formed intermediate and bottom waters. Upwelling and subduction
39 rates depend on surface forcing, mixed layer depths, and the spatial and temporal distribution of
40 surface outcrop positions of density classes (Marshall 1997; Abernathey et al. 2016). Oceanic
41 submesoscale motions are known to significantly impact upper ocean stratification and exchange
42 between the mixed layer and thermocline (Klein and Lapeyre 2009; McWilliams 2016). The
43 submesoscale is distinguished by Richardson and Rossby numbers approaching $O(1)$. Unlike low-
44 Ro , large-scale flows, which drive horizontal stirring of large-scale buoyancy and tracer gradients,
45 submesoscale motions lead to large vertical velocities and fluxes (Mahadevan and Tandon 2006).

46 The Southern Ocean and the Antarctic Circumpolar Current (ACC) are associated with many
47 of the characteristics that are conducive to generating submesoscale motions: (i) persistent frontal
48 currents with strong lateral buoyancy gradients, (ii) strong surface forcing, (iii) vigorous stirring
49 by an energetic mesoscale eddy field, and (iv) weak vertical stratification. While much of our
50 understanding about submesoscales has been achieved through idealized modeling approaches,
51 (e.g. Boccaletti et al. 2007; Capet et al. 2008; Thomas and Ferrari 2008; Mahadevan et al. 2010),
52 regional, submesoscale-resolving simulations in the Southern Ocean, such as around Kerguelen
53 Plateau (Rosso et al. 2014) and Drake Passage (Bachman et al. 2017b), have demonstrated the
54 impact of these scales on upper ocean stratification and vertical exchange with the ocean interior.
55 In particular, Rosso et al. (2014) reports enhanced vertical exchange and velocities when subme-
56 soscales are resolved, while Bachman et al. (2017b) shows that mixed layers shoal with increased
57 model resolution.

58 Observations of the submesoscale in the Southern Ocean are sparse due to the difficulty and
59 expense of field campaigns in this region. Even in Drake Passage, which is the most intensively
60 studied region of the Southern Ocean (Meredith et al. 2011), observations are typically carried out
61 on large temporal and spatial scales, such as the repeat expendable bathythermograph sections of
62 Drake Passage (Sprintall 2003) and the UK-led SR1b line. Little observational work is available
63 at the submesoscale to corroborate the modeling work that has been done in the region. Adams
64 et al. (2017) provides a notable exception; this field program surveyed an active submesoscale
65 field surrounding a large coherent mesoscale eddy pinched off from the Polar Front. New analysis
66 of high-resolution model output by Su et al. (2018) suggests that the Southern Ocean also has
67 the smallest seasonal cycle of submesoscale activity. In contrast to *in situ* studies in subtropical
68 regions which predominantly found submesoscale activity in wintertime (e.g. Callies et al. 2015;
69 Thompson et al. 2016; Hosegood et al. 2013), we present evidence for intermittent episodes of a
70 highly active submesoscale field during summer months in Southern Drake Passage.

71 In recent years, autonomous underwater vehicles, such as Seagliders, have been increasingly
72 used as a method of observing submesoscale dynamics over longer time periods than is allowed
73 by ship-based field campaigns. A 2008 observational study in the North Atlantic used gliders to
74 provide evidence for an eddy-driven restratification of the upper ocean that spurred spring phy-
75 toplankton blooms in the North Atlantic (Mahadevan et al. 2012). More recently, the 2012–13
76 OSMOSIS campaign studied a small patch of the open ocean for an entire year, documenting a
77 range of submesoscale instabilities (Thompson et al. 2016). Todd et al. (2016) used gliders to
78 study the potential vorticity (PV) structure of the North American Western Boundary Currents,
79 and du Plessis et al. (2017) carried out similar analyses in the ACC’s Subantarctic Zone.

80 The goals of the field program presented here, Changes in Stratification at the Antarctic Penin-
81 sula (ChinStrAP), were to observe mixed layer depth variability and its impact on the ventilation

82 and subduction of near-surface water masses at submesoscale temporal and spatial resolution.
83 ChinStrAP provides the first submesoscale-resolving seasonal-scale observational experiment in
84 Drake Passage, collected by Seagliders over a period of 4 months in the austral summer of 2014–
85 15. The gliders sampled on either side of the Shackleton Fracture Zone (SFZ), providing insight
86 into two distinct dynamical regimes. Upstream of the SFZ, the Southern Boundary of the ACC
87 (SBACC) and the Southern ACC Front (SACCF) are strongly constrained by topography close to
88 the shelf, but deflect northward as they pass over the SFZ (Orsi et al. 1995). The injection of Wed-
89 dell Sea Waters by the Antarctic Slope Front (ASF) (Gill 1973; Jacobs 1991) and Weddell Front
90 downstream of the SFZ (Heywood et al. 2004; Thompson et al. 2009) lead to further differences in
91 properties between the regions (Patterson and Sievers 1980; Whitworth et al. 1994). Although we
92 cover a relatively small region of the Southern Ocean, these observations show abrupt changes in
93 the characteristics of the submesoscale motions and their impact on the upper ocean hydrography;
94 lessons from this region may be extended to other parts of the Southern Ocean.

95 Following earlier observational studies, we analyze the glider data for instances where the ocean
96 is preconditioned towards gravitational and/or symmetric instability in the mixed layer. Symmetric
97 instability is a shear instability that extracts kinetic energy from geostrophic flows via slant-wise
98 convection. The resulting rearrangement of water parcels leads to low PV in the mixed layer, con-
99 ditioning it to further submesoscale instabilities (Haine and Marshall 1998). We also investigate
100 the relative impacts of mixed layer baroclinic instability (BCI), which shoals the mixed layer by
101 the slumping of isopycnals (Haine and Marshall 1998), and Ekman buoyancy flux, or wind-driven
102 re- and de-stratification (Thomas 2005). When a wind stress is applied in a down-front orientation,
103 the resulting Ekman transport carries denser water over lighter waters, causing vertical convection
104 and a destruction of stratification and PV. When the wind has an up-front orientation, the Ekman
105 transport moves lighter water over denser water, causing an increase in stratification throughout

106 the Ekman layer depth, which can lead to a restratification of the mixed layer. Parameterizations
107 are used to compare the potential effects of Ekman buoyancy flux and BCI on the mixed layer
108 buoyancy budget. As in du Plessis et al. (2017), we use a 1-D mixed layer model to discern the
109 role of surface forcing on setting upper ocean stratification. The model is then modified to incor-
110 porate the effects of Ekman buoyancy flux and BCI. Our results suggest that these processes are
111 at least as important as the surface wind and buoyancy forcing in setting mixed layer variability
112 in the Southern Ocean. Finally, a high-resolution global circulation model is used to validate our
113 mixed layer observations and to confirm the feasibility of calculating PV from gliders.

114 The paper is organized as follows. Section 2 contains a description of the ChinStrAP field
115 program, a description of the supplementary datasets used, the theoretical framework used to
116 quantify the effects of submesoscale processes on the stratification of the upper ocean, and a brief
117 description of the bulk mixed layer model used to replicate the observed mixed layers. Section 3
118 provides a characterization of the study site using previously-derived parameterizations to examine
119 the spatial and temporal variability of submesoscale instabilities, and evaluates the efficacy of the
120 mixed layer model. Section 4 further analyzes the variability across Shackleton Fracture Zone
121 (SFZ), a prominent bathymetric feature off the tip of the Antarctic Peninsula and proposes the
122 cause of the dynamical differences between the regions just upstream and downstream of the SFZ.
123 Here we also discuss the limitations of the study. Our conclusions are presented in Section 5.

124 **2. Methods**

125 *a. Field program description*

126 Two key foci of the ChinStrAP field campaign were (i) identifying regions of southern Drake
127 Passage that may be conditioned for submesoscale instabilities and (ii) determining the relative

128 importance of submesoscale motions and atmospheric forcing on the upper ocean stratification.
129 Two Seagliders were deployed north of the Antarctic Peninsula and piloted in cross-shelf sections
130 over a period of four months (December 2014 to April 2015) (Figure 1a–b). Shipboard Rosette
131 CTD casts conducted during the glider deployment cruise were used for glider sensor calibration
132 and initialization of the PWP model (Section 3d, Figure 8a).

133 The gliders profile in a V-shaped pattern, sampling continuous, inclined profiles to either 1000 m
134 or the ocean floor, whichever depth was shallower. A full-depth dive took approximately 5 hours to
135 complete, and spanned a horizontal displacement of between 0.1–7 km, depending on the strength
136 of the background flow (Figure 1c). A full transect across the shelf was completed over a period
137 of roughly one week. During each dive, measurements of temperature, pressure, and salinity
138 data were collected from a Seabird SBE3 temperature sensor and a SBE4 conductivity sensor
139 (CTSail). The unpumped CTD sampled every 5 seconds throughout the dive, approximately every
140 1 m. The initial accuracy of the temperature and salinity is approximately 0.002°C and 0.002 psu,
141 respectively, with expected drifts over the deployment of less than 0.001°C and 0.001 psu. Both
142 gliders were additionally equipped with an Aanderaa 4330F oxygen optode, and a WET Labs ECO
143 Puck measuring fluorescence and optical backscatter; an analysis of subduction pathways based
144 on the optical data is given in Erickson et al. (2016).

145 The raw glider data were processed using the University of East Anglia’s Seaglider Toolbox,
146 which corrects for lag and inertial effects, then were manually despiked. These data were objec-
147 tively mapped onto a regular grid in depth and time, with a vertical resolution of 5 meters and a
148 horizontal temporal resolution of approximately 1 hour (using a Gaussian weighting function with
149 a vertical scale of 15 m and a temporal scale of 4 hours). A comparison of the raw data to the
150 objectively mapped dataset revealed no significant aliasing due to this choice of resolution; a sen-
151 sitivity study on the horizontal grid showed this resolution to introduce minimal spurious features

152 while retaining the most information about submesoscale processes. The horizontal glider posi-
153 tion was interpolated to this grid to give a monotonically-increasing along-track distance, from
154 which horizontal spatial gradients could be calculated. This dataset necessarily conflates spatial
155 and temporal variability, and it remains a significant challenge to separate out these effects in our
156 analysis; we appeal to a high-resolution numerical model to provide additional confidence in our
157 analysis.

158 Glider SG-W was deployed north of King George Island at 58.82°W, 61.73°S, and completed
159 771 dives over a four-month period. The second glider, SG-E, was deployed northeast of Elephant
160 Island at 52.48°W, 60.48°S, and completed 642 dives over three months. The two locations are
161 separated by the SFZ, a large bathymetric ridge that runs northwest-southeast perpendicular to
162 the mean flow of the ACC through Drake Passage (Figure 1). Throughout the deployment, SG-W
163 predominantly sampled the region upstream of the SFZ, while SG-E remained mainly downstream
164 of the SFZ. Both regions, occupying the same latitudes, experience roughly the same surface heat
165 and surface wind stress. The winds are predominantly westerly and due not vary significantly over
166 the area the gliders sampled. This work considers the influence of submesoscale instabilities on
167 the mixed layer depth and surface buoyancy budget. The mixed layer depth was calculated using
168 a density threshold criterion using $\Delta\sigma = 0.125 \text{ kg m}^{-3}$ (Monterey and Levitus 1997); this value
169 was chosen because it gave the best visual agreement with the surface mixed layer in individual
170 profiles.

171 *b. Additional data sets*

172 Wind speed and wind direction data were available four times daily from ECMWF ERA-Interim
173 reanalysis (Dee et al. 2011), which has a horizontal resolution of ~80 km. ECMWF was selected
174 because it most accurately reproduced both wind speed and direction as measured by the shipboard

175 instruments over a one-week period during the deployment cruise (Figure 2b). Freshwater and
176 surface heat fluxes were also taken from ECMWF to be consistent with the wind stress data.

177 *c. Mixed layer model description*

178 In the following data set we explore the impact of lateral (or three-dimensional) submesoscale
179 dynamics on setting the upper ocean stratification. This was achieved by first using the one-
180 dimensional Price-Weller-Pinkel bulk mixed layer model (PWP) proposed by Price et al. (1986);
181 a similar analysis was carried out by du Plessis et al. (2017) for a different region of the Southern
182 Ocean. Precipitation, longwave radiation, and sensible and latent heat are applied at the surface,
183 while shortwave radiation is absorbed at depth with two wavelength-dependent exponentially-
184 decaying terms, with these attenuation distances defined by Paulson and Simpson (1977). Tur-
185 bulent mixing is parameterized based on the strength of the local wind stress. The surface fluxes
186 and wind stress were interpolated to the glider position at each time step. Using a time step of 1
187 hour, surface buoyancy and momentum fluxes are applied and mixed down through the water col-
188 umn, and bulk and gradient Richardson numbers are calculated. If these are below critical values
189 ($Ri_b < 0.65$; $Ri_g < 0.25$ as in Price et al. (1986)), water is entrained from below and the process is
190 repeated.

191 The PWP model was initialized with the shipboard CTD calibration cast, as the higher vertical
192 resolution acquired by the CTD (1 m as opposed to 5 m from the glider) was found to improve
193 the performance of the model; there was little difference between glider and CTD profiles at this
194 location. In order to distinguish the effects of atmospheric forcing from those of submesoscales,
195 advection, and other three-dimensional processes, a modified PWP model (hereafter, mPWP) was
196 also run, which included parameterizations of an equivalent heat flux from baroclinic instability

197 and Ekman buoyancy flux, detailed in Section 2e. The implementation of the mPWP will be
 198 discussed further in Section 3d.

199 *d. Potential vorticity calculations*

200 We follow the framework of earlier studies (Thomas et al. 2013; Thompson et al. 2016;
 201 du Plessis et al. 2017) that have used the Ertel potential vorticity (PV) as a diagnostic tool to
 202 determine times when portions of the mixed layer may be preconditioned towards instabilities that
 203 will act to restore PV to neutral stability conditions. A brief summary of this technique is provided
 204 here. The full Ertel PV is given by

$$q_{Ertel} = \boldsymbol{\omega}_a \cdot \nabla b = (f + \zeta)N^2 + (w_y - v_z)b_x + (u_z - w_x)b_y, \quad (1)$$

205 where $\boldsymbol{\omega}_a = 2\boldsymbol{\Omega} + \nabla \times \mathbf{u}$ is the absolute vorticity, b is the buoyancy, defined as $b = g(1 - \rho/\rho_0)$
 206 with ρ_0 as a reference density 1027.15 (the mean density over the deployment), $\boldsymbol{\Omega}$ is the angular
 207 velocity of the Earth, \mathbf{u} is the three-dimensional fluid velocity, $N^2 = b_z$ the vertical stratification,
 208 and $\zeta = v_x - u_y$, the vertical relative vorticity. Subscripts above indicate partial differentiation.

209 A limitation of the PV approach is that observations are restricted to the vertical and a single hor-
 210 izontal dimension (Shcherbina et al. 2013; Thompson et al. 2016). During this particular mission,
 211 the gliders were piloted perpendicular to the fronts to the degree possible based on the current
 212 speeds; this limits the error in the two-dimensional PV calculation (see Section 4). A compre-
 213 hensive explanation behind the simplifying assumptions made can be found in Thompson et al.
 214 (2016), among others. The resulting observational PV is given as

$$q_{Obs} = (-v_z, 0, f + v_x) \cdot (b_x, 0, b_z) = (f + \zeta)N^2 - \frac{b_x^2}{f}, \quad (2)$$

215 and the validity of these assumptions will be discussed in Section 4.

216 From the PV calculations, conditions favorable for submesoscale instabilities can be identified
 217 using the balanced Richardson number, as in Thomas et al. (2013):

$$\phi_{Ri_b} = \tan^{-1}(-Ri_b^{-1}), \quad (3)$$

218 with a critical balanced Richardson angle, $\phi_c = \tan^{-1}\left(-\frac{\zeta}{f}\right)$, separating regimes of symmetric,
 219 gravitational, and mixed symmetric/gravitational instability from the stable regime.

220 *e. Submesoscale instability calculations*

221 In addition to the instability criteria described above, which require $PV > 0$ (opposite sign of
 222 f), the release of available potential energy stored in the mixed layer through BCI, which does
 223 not require $PV > 0$, may also impact the upper ocean stratification (Boccaletti et al. 2007). Fox-
 224 Kemper et al. (2008) provided a parameterization for the effective streamfunction caused by this
 225 baroclinic instability dependent on the mixed layer depth H and horizontal buoyancy gradient,
 226 $|\nabla b|$. As the gliders can only resolve one horizontal direction, we can write the parameterization
 227 as

$$\psi_{BCI} = C_0 \frac{b_x H^2}{f} \mu(z), \quad (4)$$

228 with b_x being the horizontal buoyancy gradient in the direction along the glider track. The empir-
 229 ical constant C_0 may vary throughout the ocean, but in the absence of any direct measurements
 230 of this value, we take $C_0 = 0.06$ as in Fox-Kemper et al. (2008) and previous glider studies. The
 231 function $\mu(z)$ describes the vertical structure of ψ_{BCI} ; here we set this term equal to unity for
 232 simplicity. Using ψ_{BCI} and the lateral buoyancy gradient, the re-stratifying buoyancy flux can be
 233 determined, and for ease of comparison to the surface fluxes, as in Mahadevan et al. (2012), this
 234 can be expressed as an equivalent heat flux (W m^{-2}):

$$Q_{BCI} = 0.06 \frac{b_x^2 H^2 C_p \rho_0}{f \alpha g}, \quad (5)$$

235 where C_p is the specific heat of seawater and α is the thermal expansion coefficient, a function of
236 temperature and pressure.

237 Another key factor in setting the stratification of the upper ocean is the the interaction be-
238 tween surface wind forcing and upper ocean fronts, a process known as the Ekman buoyancy
239 flux (Thomas 2005). This effect can also be written as an overturning streamfunction, again with
240 the simplification that we only consider the wind stress component perpendicular to the glider
241 path:

$$\Psi_{EBF} = \frac{\tau^y}{\rho_0 f}. \quad (6)$$

242 If we again consider the buoyancy gradient in the along-track direction, b_x , we can write an equiv-
243 alent heat flux expression analogous to (5),

$$Q_{EBF} = -\frac{b_x \tau^y C_p}{f \alpha g}. \quad (7)$$

244 We acknowledge that our analysis disregards much of the intricacy of the vertical structure of
245 the upper ocean, in particular, by eliminating the depth-dependence of the Q_{BCI} parameterization
246 (5) and by assuming the equivalence of the Ekman layer and mixed layer depths. Nonetheless,
247 observational evidence from Lenn and Chereskin (2009) supports the notion that in Drake Passage,
248 Ekman layer depths approach the annual-mean mixed layer depths of 120 m. Disentanglement of
249 the vertical structure is beyond the scope of the paper, and we will focus on the parameterizations
250 in terms of relative, rather than absolute, changes.

251 *f. Global circulation model description*

252 Output from a global high-resolution general circulation model based on a
253 Latitude/Longitude/polar-Cap (hereafter LLC) configuration of the MIT general circulation
254 model (MITgcm; Marshall et al. (1997); Hill et al. 2007) is used to assess the validity of our

255 glider PV analysis. The LLC simulation is a $1/48^\circ$ MITgcm model with 90 vertical levels, with a
256 horizontal resolution of approximately 0.75 km in the polar regions and a vertical resolution of 1
257 m near the surface to better resolve the diurnal cycle.

258 The model configuration includes a flux-limited, seventh-order, monotonicity-preserving advec-
259 tion scheme (Daru and Tenaud 2004) and the modified Leith scheme of Fox-Kemper and Mene-
260 menlis (2008) for horizontal viscosity. Vertical viscosity and diffusivity are parameterized accord-
261 ing to the K-profile parameterization (KPP) (Large et al. 1994). Bottom drag is quadratic (drag
262 coefficient, $C_D = 2.1 \cdot 10^{-3}$) and side drag is free slip. Partial cells (Adcroft et al. 1997) are used
263 to represent the sloping sea floor in our z-level vertical discretization. Bathymetry is from Global
264 Topography v14.1, updated from Smith and Sandwell (1997).

265 The simulation is initialized from a data-constrained global ocean and sea ice solution provided
266 by the Estimating the Circulation and Climate of the Ocean, Phase II (ECCO2) project (Mene-
267 menlis et al. 2005, 2008; Losch et al. 2010) and includes tidal forcing. The inclusion of tides
268 allows to successfully reproduce shelf-slope dynamics and water mass modification (Flexas et al.
269 2015). Surface boundary conditions are 6-hourly output from the ECMWF atmospheric opera-
270 tional model analysis, starting in 2011, with spatial resolution of about 79 km. One year of hourly
271 model output of full 3-dimensional model prognostic variables is available (from September 2011–
272 August 2012).

273 We used three subdomains: one located upstream of the SFZ, one located between the SFZ
274 and the Ona Basin, and one located downstream of both the SFZ and the Ona Basin, plotted on
275 Figure 1b. Comparisons between the observations and the LLC model were made in order to vali-
276 date the assumptions made in our calculations of potential vorticity (PV) and MLD. Temperature,
277 salinity, and horizontal velocities from the model were used to calculate both the Ertel PV (1) and
278 an observational PV (2).

279 **3. Results**

280 *a. Site characterization*

281 The observations collected in the ChinStrAP field program allow for the examination of both
282 temporal (summer and into early fall) and spatial variability of mixed layer depths and dynamics.
283 Following Whitworth et al. (1998), we define Circumpolar Deep Water (CDW) as the subsurface
284 temperature maximum (θ_{max}). In our region, θ_{max} corresponds to a neutral density (γ^{θ}) of 28.00
285 kg m^{-3} . Water above CDW is Antarctic Surface Water (AASW), and subsurface θ_{min} indicate
286 presence of Winter Water (WW) formed during the cold season.

287 Upstream of the SFZ, the mixed layer depth does not vary significantly, and it is clearly defined
288 by the shallow, warm/fresh AASW that sits above WW (Figure 3a). Downstream of the SFZ, the
289 mixed layers are much more variable and there are sharp lateral gradients in the density field that
290 are not associated with the main fronts of the ACC. This is indicative of enhanced stirring by an
291 active mesoscale eddy field (Figure 3b). In both representative sections, warmer surface waters
292 are found offshore than on the shelf; this pattern is also reflected in the high-resolution SST data
293 shown in Figure 1b.

294 The predominant watermass upstream of the SFZ is CDW, which is found all the way up to the
295 shelf break. It is capped by a layer of AASW on top of WW, which leads to the stability in the
296 mixed layer described above. Downstream of the SFZ, there is weak vertical stratification, but
297 there are sharp distinctions between the subsurface watermasses in the horizontal as evidenced by
298 the gaps in the T/S structure that are not evident upstream (Figure 3c–d).

299 One of the strongest distinctions between the two regions is the depth and variability of the
300 mixed layers upstream and downstream of the SFZ. The mixed layer depths upstream of the SFZ
301 are 65 ± 19 m, while downstream the average depth is 119 ± 92 m. Furthermore, upstream of the

302 SFZ, mixed layer depth has an inverse correlation with bathymetry, with deeper mixed layers being
303 found on the continental shelf/slope and shallower mixed layers as the glider moves into deeper
304 waters (Figure 4a). In contrast, mixed layers downstream of the SFZ show more spatial variability,
305 with a general trend of increasing mixed layer depth from west to east downstream of the SFZ. SG-
306 E occupied these stations further downstream from the SFZ at the beginning of the deployment.
307 Since mixed layers would be expected to be deeper in autumn, towards the end of the deployment
308 (Figure 4b), we attribute this pattern to spatial, rather than temporal variability. While the peak in
309 the histogram of the mixed layer depths is similar in both regions, there is a much longer tail in the
310 mixed layer depth distribution in the region downstream of the SFZ as compared to the upstream
311 region (Figure 5a). The glider sampled very deep mixed layers on the shelf downstream of the
312 SFZ, where stratification is low. Previous works (e.g., Patterson and Sievers (1980)) have shown
313 that deep mixed layers in this region are not restricted to wintertime, as lateral mixing processes
314 may lead to homogeneity through the entire water column. However, even discarding the data
315 collected over the shelf, the mixed layers downstream of the SFZ are significantly deeper than
316 those upstream.

317 *b. Mesoscale context*

318 The deflection of the SACCF over the SFZ leads to a more unstable front downstream of the
319 SFZ than upstream, where the front follows bathymetry, essentially being steered by contours
320 of f/h . Similarly, the SBACC, which is also topographically-steered upstream of the SFZ, is
321 deflected around the Ona Basin just downstream of the SFZ (Orsi et al. 1995), which may impart
322 additional variability (Barré et al. 2008). The area to the east of the SFZ and surrounding Elephant
323 Island, known as the Weddell-Scotia Confluence, is also prone to increased variability due to
324 the interaction of a number of distinct boundary currents. In addition to the SBACC, the ASF

325 sheds eddies and filaments off Ona Ridge (Flexas et al. 2015), and the Antarctic Coastal Current
326 circulates between the Antarctic Peninsula and the northern islands before meeting up with the
327 ASF (Palmer et al. 2012). The injection of Weddell Sea waters and the shedding of Weddell
328 eddies downstream of the SFZ also results in a region that, while close in distance to the upstream
329 region, is much more energetic (Palmer et al. 2012; Thompson and Youngs 2013).

330 The horizontal buoyancy gradients exhibit significant variability upstream and downstream of
331 the SFZ. The horizontal buoyancy gradient was calculated as the average over the mixed layer
332 depth, discarding the top 5 meters. Upstream of the SFZ, the largest values of b_x are located near
333 the positions of the SBACC. Downstream, the high values of b_x are not constrained to the mean
334 frontal positions, and are indicative of a more energetic meso- and submesoscale field (Figure 4c–
335 d, fronts located using AVISO and the contours specified in Kim and Orsi (2014)). A comparison
336 of the histograms of the horizontal buoyancy gradients in both regions reveals a significant offset
337 between the two curves, with the downstream region more likely to exhibit larger gradients (Fig-
338 ure 5c). This result is robust to the choice of mixed layer depth criterion. The zonal wind stress
339 is virtually identical between the two regions (Figure 5b) and therefore this surface forcing alone
340 can not explain the spatial variability in submesoscale activity.

341 *c. Upper-ocean restratification processes*

342 Glider data and ECMWF reanalysis winds are used to determine the effects of surface forcing
343 and submesoscale processes on the stratification of the upper ocean, as detailed in Section 2e. The
344 parameterizations of Fox-Kemper et al. (2008) and Thomas (2005) are used to calculate equivalent
345 heat fluxes caused by BCI and Ekman buoyancy forcing, respectively (Figure 6), which are then
346 compared to the surface heat flux Q_{surf} . Since the two gliders are at roughly the same latitude
347 and the cloud cover across the SFZ is similar throughout the deployment, Q_{surf} is approximately

348 the same across the two regions. There is a strong diurnal cycle but the forcing over the study
349 period warms the surface ocean with a mean value of $Q_{surf} = 188 \text{ W m}^{-2}$. The surface heat
350 flux decreases from summer into early fall during the deployment, with the mean over the first
351 third of the deployment $Q_{surf} = 197 \text{ W m}^{-2}$ and the mean over the last third of the deployment
352 $Q_{surf} = 63 \text{ W m}^{-2}$. The magnitudes of Q_{BCI} and Q_{EBF} are larger, with mean values of 580 W
353 m^{-2} and 273 W m^{-2} , respectively (Figure 7). Upstream of the SFZ, the equivalent heat flux
354 extrema are intermittent, happening roughly once per week, associated with the deeper mixed
355 layers and strong horizontal buoyancy gradients near the shelf break (Figure 4a,c). Downstream
356 of the SFZ, large values of Q_{BCI} are more frequent. The large contribution of BCI to the total
357 heat flux (Figure 7c) suggests that baroclinic instability should have a leading order impact on
358 setting the mixed layer depth. The contributions of these submesoscale heat fluxes to upper ocean
359 stratification are explored in the following section.

360 *d. Modeling the observed mixed layers*

361 The PWP model was previously shown to accurately reproduce mixed layer depths in regions
362 such as the North Pacific (Price et al. 1986) and the tropical Indo-Pacific (Shinoda and Hendon
363 1998). However, the ChinStrAP region was characterized by an abundance of lateral processes,
364 which are not captured by the traditional PWP model. We hypothesize that by incorporating
365 the effect of these 2-dimensional processes into a modified PWP model, the model will perform
366 better in capturing mixed layer depth variability. Indeed, the unmodified PWP model results in
367 mixed layer depths that are significantly deeper than those observed by the glider. For SG-E, the
368 PWP model outputs a mean mixed layer depth and standard deviation of $229 \pm 33 \text{ m}$, compared to
369 $119 \pm 86 \text{ m}$ as observed by the glider (a 92% error in mean and a 62% error in standard deviation

370 of the mixed layer). Not only is the modeled mean mixed layer depth significantly deeper than the
371 actual mixed layer, the mixed layer variance is not well-captured by the PWP model.

372 To improve the performance of the PWP model, we accounted for the effects of submesoscale
373 motions via the parameterizations for Q_{EBF} and Q_{BCI} (described in Section 2e). These two terms
374 were combined into a forcing term that is applied equally over the mixed layer depth at each time
375 step in the model, Q_{sub} , given as

$$Q_{sub} = Q_{EBF} + Q_{BCI}. \quad (8)$$

376 The result of this mPWP model is closer to the observations in terms of both mean mixed layer
377 depth and variance, providing mixed layers of 177 ± 81 m (a 6% difference from the standard devi-
378 ation of the glider observations, although still a 48% difference from the mean of the observations).
379 Although the individual mixed layer shoaling/deepening events do not match up between the ob-
380 servations and the mPWP model, the modified model does capture much of the character of the
381 observed mixed layer, with large variations of mixed layer depth over relatively short timescales
382 (Figure 8). The model output is also consistent with our findings that the submesoscales are
383 dominantly restratifying over the period of deployment, and indicates that accounting for the sub-
384 mesoscale motions is critical to correctly model mixed layer depths and variability.

385 Shoaling of the mean mixed layer throughout the sample period can be observed in both the PWP
386 and mPWP models, although the effect is much more pronounced for the mPWP configuration.
387 Large et al. (1994) discuss the need for advection of cold water and salt into mixed layer models
388 to offset the long-term drifts caused by net surface heating/freshwater flux. mPWP exhibits a
389 larger shoaling over the model run as there is a greater (equivalent) heat flux being applied to the
390 surface. The mPWP model captures the transition from deep to shallow mixed layers observed by
391 the glider moving from December/January into the end of the summer, while the standard PWP
392 model does not. Remaining differences between the observations and the mPWP model can be

393 attributed to other processes, such as Langmuir circulations, or wave-forced turbulence, which
394 have been shown by Belcher et al. (2012) to play a significant role in setting mixed layer depths
395 in the Southern Ocean. Similarly, lateral advection and large-scale gradients in the background
396 stratification are not captured in the model, and may also help to explain some of the remaining
397 discrepancies.

398 *e. Variation of instabilities*

399 There is also significant variation between the two regions with regards to the types of instabili-
400 ties the mixed layer is conditioned to undergo, as described in Section 2e (Figure 9). A comparison
401 of the two time series of submesoscale instabilities shows that the region upstream of the SFZ is
402 more susceptible to gravitational instability. In contrast, the area downstream of the SFZ experi-
403 ences frequent, but intermittent, episodes that would indicate symmetric instability, sometimes ex-
404 tending through the whole mixed layer (Figure 9b). The spatial pattern of instabilities (Figure 9c)
405 shows that symmetric instability is favored both on- and off-shelf downstream. Upstream of the
406 SFZ, periods of conditioning of 25% or more of the mixed layer towards gravitational instability
407 occur 28% of the time. This is especially common far from the shelf break. These classifications
408 are consistent with Adams et al. (2017), who observed conditions suitable for gravitational and
409 symmetric instabilities during early fall in the Scotia Sea. We propose that the enhancement of
410 gravitational instability upstream of the SFZ can in part be attributed to the persistent forcing of
411 the ACC's topographically-steered fronts by down-front winds. On a dive-by-dive basis, it may
412 not be possible to identify forcing factors contributing to a certain type of instability conditioning,
413 however, there is a larger-scale pattern aligning periods of gravitational instability with higher EBF
414 off the shelf (as compared to on-shelf), as seen in Figure 6. We leave a more in-depth investigation
415 of the mechanisms behind the specific instabilities to a future work.

416 *f. Validation of glider-based PV calculations*

417 The calculation of PV from the Seagliders requires the gliders to be piloted perpendicular to
418 the orientation of the front. This requires the following assumptions: (a) variation in the along-
419 front direction is negligible and (b) velocities across the front are negligible. With the additional
420 assumption that vertical velocities are small, we obtain an expression for observational PV (2).
421 In order to verify the validity of these simplifications, the LLC 1/48° GCM was utilized. Three
422 subdomains over the deployment area were extracted from the model output, comprising over 150
423 sections. The full Ertel PV and the observational PV calculated from these transects show many of
424 the same structures; the amplitude of the observational PV estimates tend to be smaller than the full
425 PV, especially in the mixed layer (Figure 10a–b). These calculations were performed within the
426 top 200 meters depth using snapshots every two hours over a period of 5 days for each subdomain.
427 Comparing the signs of the respective PV calculations reveals the same sign at 92.3% of all these
428 points in space and time. False positives, or times when the observational PV indicates instability
429 but the full PV does not, occur only 2.1% of the time. As the three subdomains were chosen from
430 multiple regions with different dynamics, and calculations were performed for a range of days
431 and times, this provides additional confidence in the assumptions and thus, the PV and instability
432 calculations.

433 **4. Discussion**

434 *a. Summer submesoscale activity*

435 Previous studies have shown that the intensity of submesoscale activity can undergo a strong
436 seasonal cycle, linked to changes in the mixed layer depth and in some cases to mesoscale stirring
437 (Sasaki et al. 2014; Callies et al. 2015; Buckingham et al. 2016). Instances of symmetric instability

438 have been observed in western boundary currents (D’Asaro et al. 2011; Thomas et al. 2016) and
439 conditions suitable for symmetric instability have been documented in the subtropical open ocean
440 in both the Atlantic (Thompson et al. 2016) and Pacific (Hosegood et al. 2013) basins. However,
441 these previous studies have either focused explicitly on the winter season or have found a partic-
442 ularly vigorous submesoscale field during the winter months. This study, in contrast, took place
443 during the summer months and into the early fall, when shallower mixed layers and increased
444 stratification have previously been found to suppress submesoscale activity in other ocean basins.
445 Our findings of an active submesoscale in the Southern Ocean corroborate the results of du Plessis
446 et al. (2017), who conducted a similar survey in the Subantarctic Zone in spring–summer time.

447 In the ChinStrAP study, we found evidence supporting the existence of symmetric instability in
448 Southern Drake Passage during the austral summer (Dec.–Mar.). Favorable conditions for sym-
449 metric instability were found downstream of the SFZ for the duration of the study. The likely
450 presence and prevalence of submesoscale instabilities, even in the summertime, requires a reeval-
451 uation of the way that dynamics of this scale are considered in climate and circulation models,
452 e.g., via new parameterizations for SI put forth by Bachman et al. (2017a). As seen in Klein and
453 Lapeyre (2009), density gradients at the submesoscale can be responsible for up to 50% of the
454 vertical exchange between the mixed layer and the thermocline below. Combined with the active
455 summertime submesoscale presented here, this suggests that current models may be underestimat-
456 ing the strength of the dynamical component of the Southern Ocean biological pump.

457 *b. Spatial variations: Upstream vs. downstream of Shackleton Fracture Zone*

458 Three key components contribute to the parameterizations of Q_{EBF} and Q_{BCI} : mixed layer depth;
459 horizontal buoyancy gradient, b_x , indicative of mesoscale and submesoscale stirring; and wind
460 stress-front orientation, τ^y . While the mode of the mixed layer depth (histogram peak in Figure

461 5a) is similar across our study region, the distribution of mixed layer depths upstream of the SFZ is
462 much tighter, while downstream of the SFZ, there is a long tail on the distribution (Figure 5a). The
463 other main difference between the regions is in the horizontal (along-track) buoyancy gradient, b_x ,
464 where there is an offset between the histograms, with stronger buoyancy gradients downstream of
465 the SFZ (Figure 5b).

466 The differences in horizontal buoyancy gradients upstream and downstream of the SFZ suggest
467 different dynamical regimes, which imply differing magnitudes, types, and frequency of subme-
468 soscale instabilities. Upstream of the SFZ, there are strong events of EBF and/or BCI with a sig-
469 nificant impact on the equivalent heat budget of the upper ocean (Figure 7a,c), but these events are
470 localized to a narrow region associated with the SBACC. The topographically-constrained fronts
471 and the persistence of the westerly (down-front) winds generate the gravitational instabilities clas-
472 sified in Figure 9. In contrast, these same events downstream of the SFZ are much more frequent
473 and occur over a broader spatial extent, due to both the larger buoyancy gradients and deeper
474 mixed layers, both of which precondition the upper ocean for symmetric instability. Critically,
475 these differences occur despite experiencing the same surface forcing fields.

476 We propose that the increased submesoscale activity downstream of the SFZ is due to two main
477 factors: spatial variations in eddy kinetic energy and upper ocean stratification. Differences in the
478 surface eddy kinetic energy (EKE) are captured clearly in both satellite altimetry data as well as
479 output from the LLC (Figure 11). These patterns in EKE are strongly influenced by the bathymetry,
480 both due to the deflection of the SBACC over the SFZ and the retroflexion of the ASF exiting the
481 Weddell Sea. Both of these processes tend to generate mesoscale eddies that will increase lateral
482 stirring and induce variability at submesoscales. The LLC shows how the ACC becomes unstable
483 as it passes through the SFZ, leading to an increase in EKE downstream. This signal is weaker in
484 the observed sea surface height variability due to the much lower resolution of AVISO compared

485 to the LLC, but the observations still show that the average summertime EKE is enhanced down-
486 stream of the SFZ (Figure 11a). In addition to EKE, the large-scale circulation supports weaker
487 vertical stratification of the upper ocean downstream of the SFZ. The main cause of this is the
488 shoreward penetration of AASW upstream of the SFZ, whereas the northward deflection of the
489 SBACC limits its southward extension downstream. Thus, downstream of the SFZ, relatively ho-
490 mogeneous upper-ocean density contributes to lower PV and deeper mixed layers that store more
491 potential energy and may thus be more prone to submesoscale instabilities.

492 *c. Impact and limitations of the study*

493 Separating spatial and temporal variability in the glider data is a significant challenge. The
494 experimental design of the field program acted to counteract this in several ways. First, the simul-
495 taneous piloting of the gliders upstream and downstream of the SFZ allows the direct comparison
496 of dynamics and watermass properties between the two regions. Each glider also occupied tran-
497 sects in approximately the same location over multiple weeks; these multiply-occupied sections
498 support that variability is predominantly spatial, rather than temporal. The glider capabilities, e.g.
499 speed through the water, also influence our interpretation of these time series. First, the time to
500 complete a full transect is long compared to the timescales of submesoscale dynamics. Thus, we
501 emphasize that this study provides a statistical survey of the region and not a perfect snapshot of
502 the dynamical regime; we stress the inter-comparison of patterns, rather than the absolute magni-
503 tudes. The second is a practical matter; the glider often flew at a speed comparable to or less than
504 that of the depth-averaged current, making it difficult to fly the glider perpendicular to the front.

505 The key assumption in our calculations of equivalent heat fluxes and Richardson numbers was
506 that the gliders were flown perpendicular to the frontal structure of the ACC, which allowed us to
507 simplify PV into a two-dimensional expression. This was more successful upstream of the SFZ

508 than downstream, with SG-W maintaining relatively straight trajectories across the continental
509 shelf for the majority of the deployment (Fig. 1). Downstream of the SFZ, the frontal structure is
510 less well-defined. Because the glider tracks are less perpendicular to the shelf, it is more difficult
511 to know the glider's orientation with respect to the fronts. Critically, though, the LLC model
512 does reproduce intermittent regions in the surface mixed layer where $PV > 0$ in the summertime,
513 consistent with our observations. Furthermore, analysis of the LLC also demonstrates higher
514 propensities for conditioning towards gravitational instability upstream of the SFZ and towards
515 symmetric instability downstream of the SFZ.

516 Despite the limitations of this study, the results provide valuable insight into submesoscale vari-
517 ability in one region of the Southern Ocean. Most notably, although previous work has shown
518 the importance of submesoscale activity (e.g. Klein and Lapeyre 2009; Rosso et al. 2014), this is
519 among the first studies to show such ubiquitous submesoscale dynamics during the summertime,
520 a period when shallow mixed layers and increased stratification should act to prohibit the instabil-
521 ities explored in this study (see also du Plessis et al. (2017)). The comparison of observed mixed
522 layers and those calculated by the PWP bulk mixed layer model demonstrate the importance of
523 these dynamics in setting the mixed layer depth and stratification of the upper ocean. We have
524 also shown the existence of two very different submesoscale dynamical regimes separated by a
525 relatively small distance; conditioning by the background flow is largely influenced by the under-
526 lying bathymetry. We stress the need to characterize regional variability in the ACC. The abrupt
527 change in submesoscale character due to topography is another example of localized “hot spots”
528 that have a dynamical influence on the Southern Ocean (Abernathey and Cessi 2014; Thomp-
529 son and Naveira Garabato 2014; Dufour et al. 2015; Viglione and Thompson 2016; Tamsitt et al.
530 2016). We propose that similar dynamical shifts may occur in other regions of the Southern Ocean
531 with large topographic features, e.g., Kerguelen Plateau and the Pacific-Antarctic Ridge (Rosso

532 et al. 2014), which has implications for the localization of CO₂ uptake in the Southern Ocean. In
533 particular, because of the fine spatial structure of these upper ocean processes, long time series
534 of pCO₂ concentrations in specific locations, such as Drake Passage (Takahashi et al. 2009), may
535 provide misleading information about the Southern Ocean carbon cycle if simply extrapolated
536 circumpolarly.

537 **5. Conclusions**

538 Two Seagliders were deployed north of the Antarctic Peninsula from December 2014–April
539 2015, sampling both up- and downstream of the Shackleton Fracture Zone (SFZ). Sampling at a
540 mean horizontal resolution of 1.6 km, this study resolves the upper ocean submesoscale density
541 structure of a key region of the ocean for water mass ventilation and modification (Sallée et al.
542 2010; Abernathey et al. 2016), as well as shelf-slope exchange and water mass modification (Ruan
543 et al. 2017). Although the mesoscale eddy stirring, strong wind forcing, deep mixed layers, and
544 persistent fronts would suggest the Southern Ocean to be a hotbed for submesoscale activity, little
545 observational work has been undertaken here to validate numerical simulations (Rocha et al. 2016;
546 Adams et al. 2017). In this work, we present evidence for an active submesoscale field, even in
547 summer months, but distinct geographical differences in the characteristics of these submesoscale
548 motions. The conditions for symmetric instability are found almost exclusively downstream of
549 the SFZ, suggesting fundamental differences in the dynamics of the regions on either side of the
550 SFZ. The primary differences between the two regions are deeper mixed layers and stronger lateral
551 buoyancy gradients downstream of the SFZ. Together, these contribute to the preconditioning of
552 the downstream region for increased submesoscale activity.

553 Finally, comparisons were made between the glider observations and two different models. First,
554 the 1-D PWP bulk mixed layer model was used in an attempt to replicate the time-evolving mixed

555 layer depth. This model was seen to diverge from the observations due to its exclusion of sub-
556 mesoscale and other 3-dimensional processes. When parameterized fluxes, Q_{EBF} and Q_{BCI} , were
557 added into the surface forcing, the modified PWP model was more accurate in representing the
558 variability in the mixed layer depth time series, although the mean values were still 50% larger
559 than the observations. PV calculated from the glider observations was compared to the full Ertel
560 PV as diagnosed from the $1/48^\circ$ LLC model. The LLC was also subsampled and used to calculate
561 the PV using the same simplifications as when calculating the observed PV from the glider. These
562 results showed that while some caution must be used in calculating PV from gliders, the sign of
563 the observed PV is predominantly the same as the sign of the full PV (in 92.3% of instances, both
564 PV calculations had the same sign).

565 This work provides evidence that the submesoscale is highly active in the Southern Ocean even
566 during the summertime, significantly altering the stratification of the upper ocean with implications
567 for carbon capture and the biological pump. The intermittency of these events as well as the size of
568 the variations over short spatial scales suggest that this is a complex phenomenon that will remain
569 challenging to represent in numerical models not focused on localized regions; this is particularly
570 true for the role of submesoscale on air-sea coupling. The comparison of these observations to a
571 high-resolution model validates the use of gliders to study instabilities at this scale.

572 *Acknowledgments.* GAV and AFT were supported by NSF award OPP-1246460. JS was sup-
573 ported by NSF award OPP-1246160. SS thanks the following funding agencies: a Wallenberg
574 Academy Fellowship (WAF 2015.0186) and the South African National Research Foundation
575 (NRF), Grant SNA14071475720. The Group for High Resolution Sea Surface Temperature
576 (GHRSSST) Multi-scale Ultra-high Resolution (MUR) SST data were obtained from the NASA
577 EOSDIS Physical Oceanography Distributed Active Archive Center (PO.DAAC) at the Jet Propul-

578 sion Laboratory, Pasadena, CA (<http://dx.doi.org/10.5067/GHGMR-4FJ01>) The ERA-Interim data
579 were obtained from ECMWF. The authors would like to thank the Antarctic Support Contract staff
580 as well as the captains and crews of the ARSV Laurence M. Gould and the RRS Ernest Shackleton
581 for their support during the deployment and recovery cruises.

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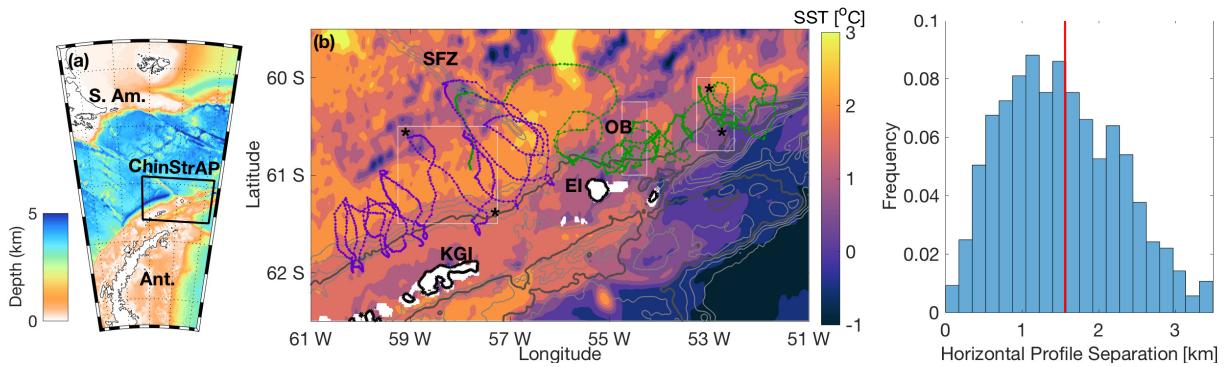
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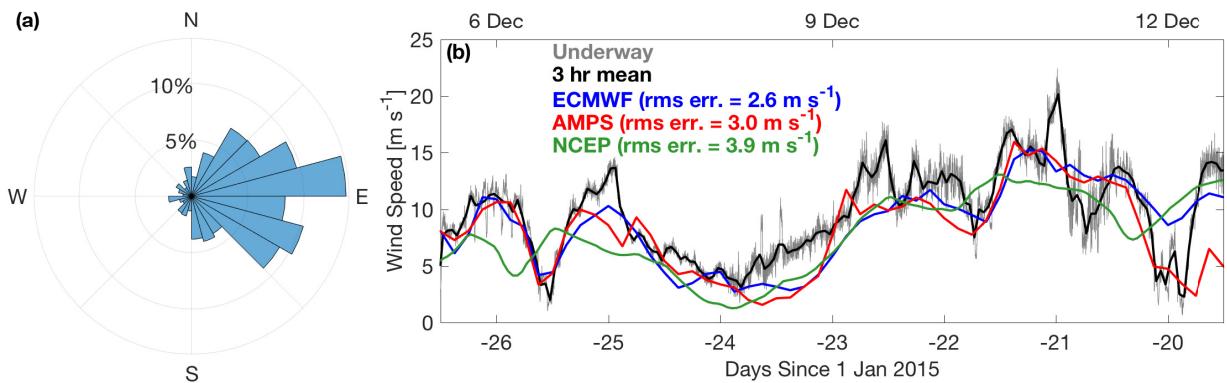
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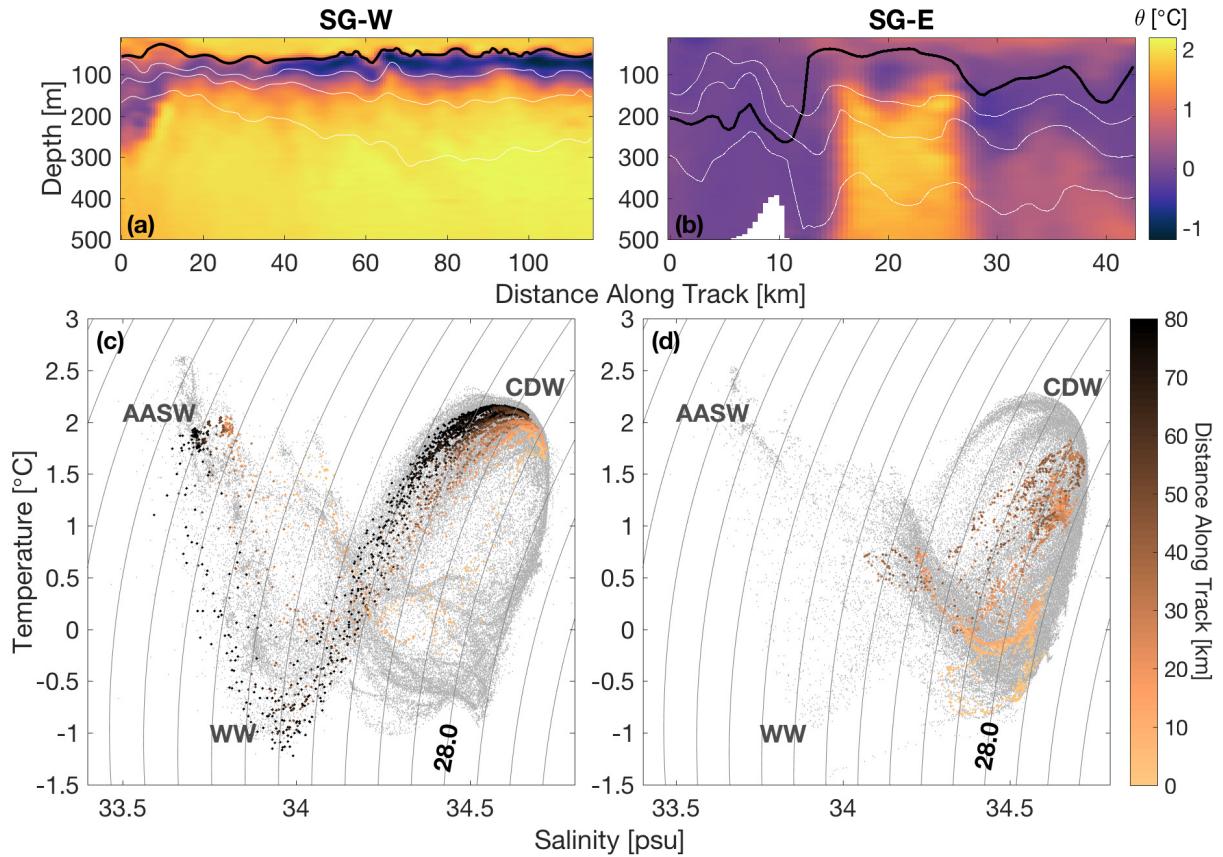
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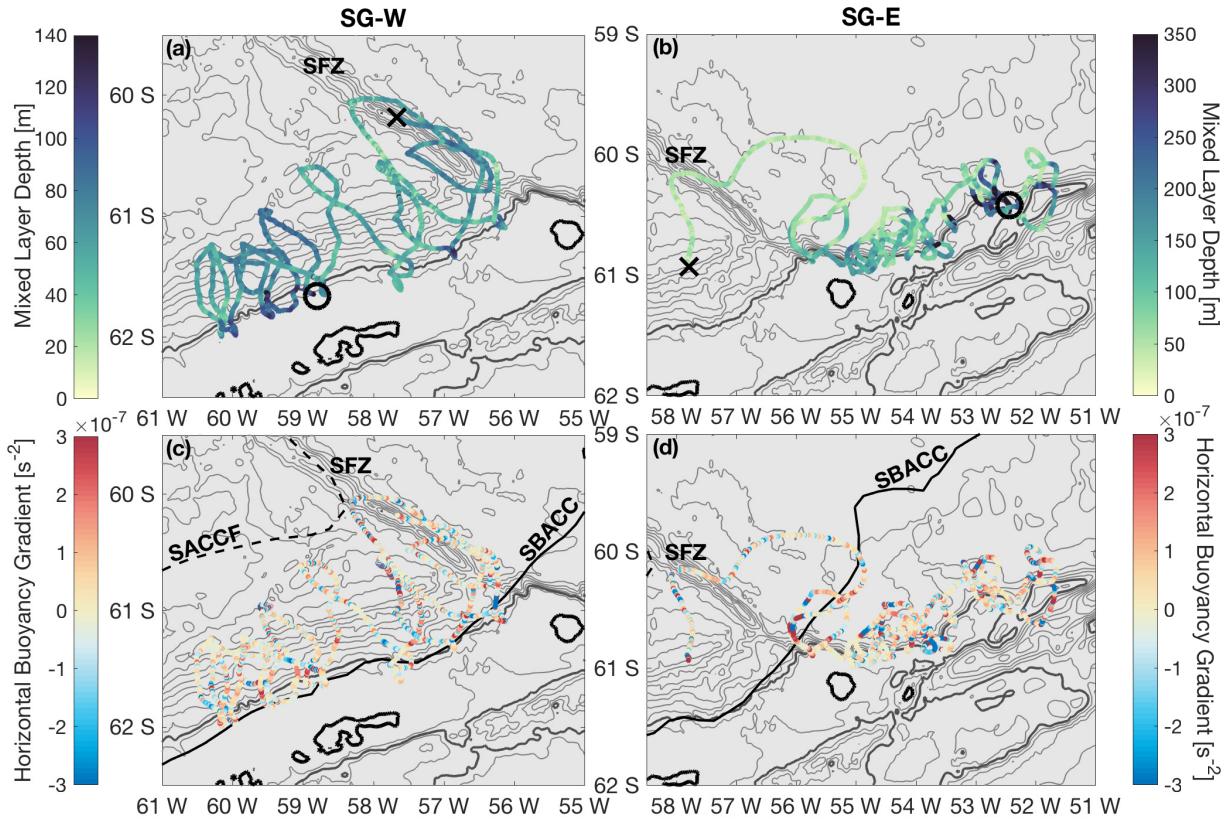
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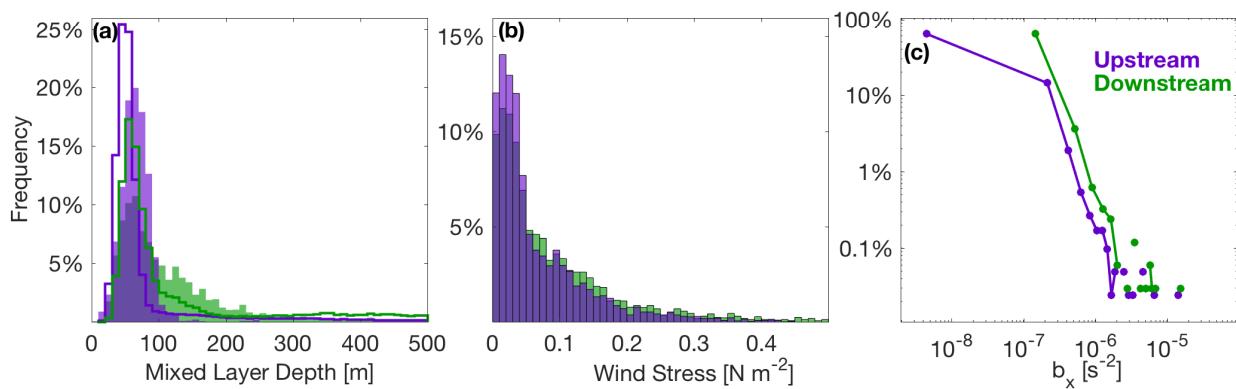
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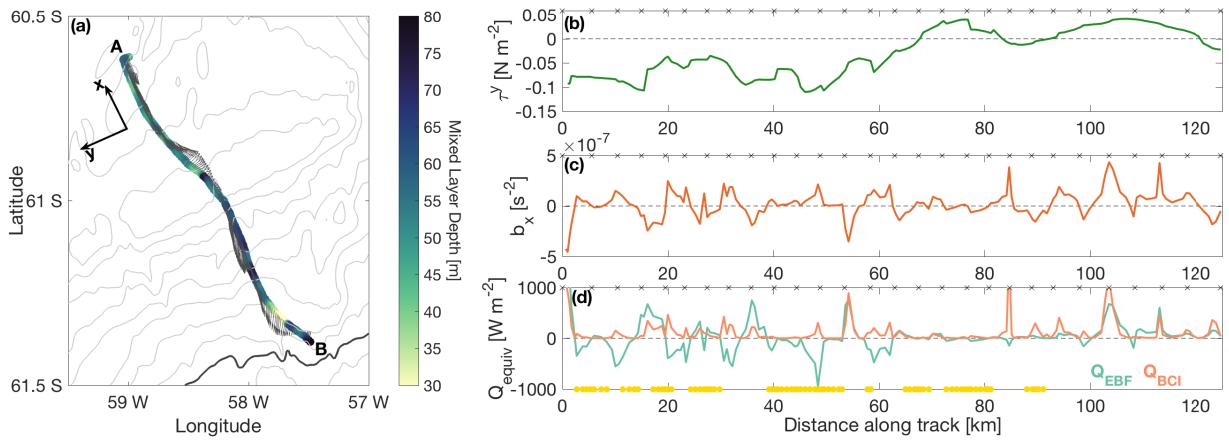
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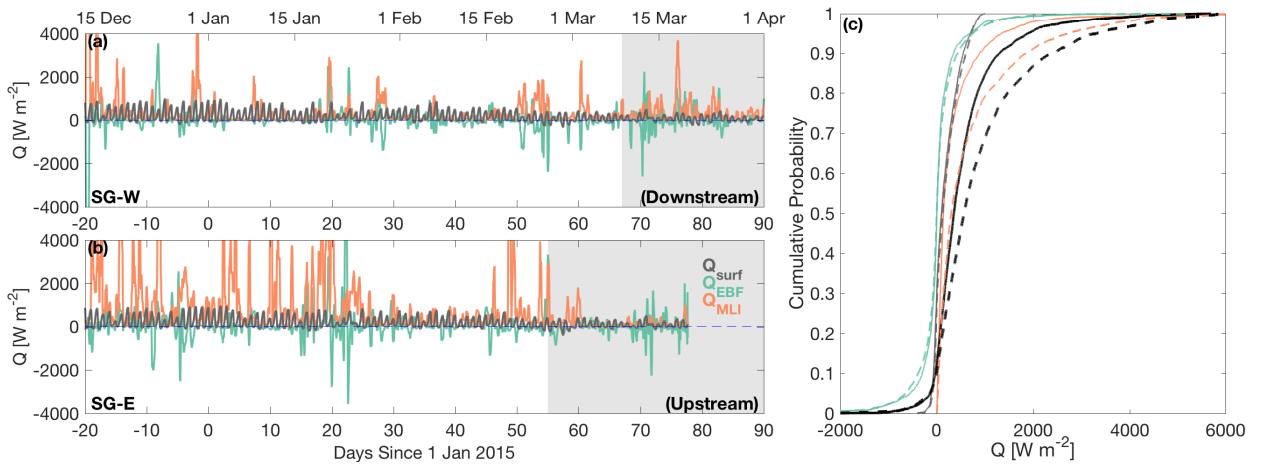
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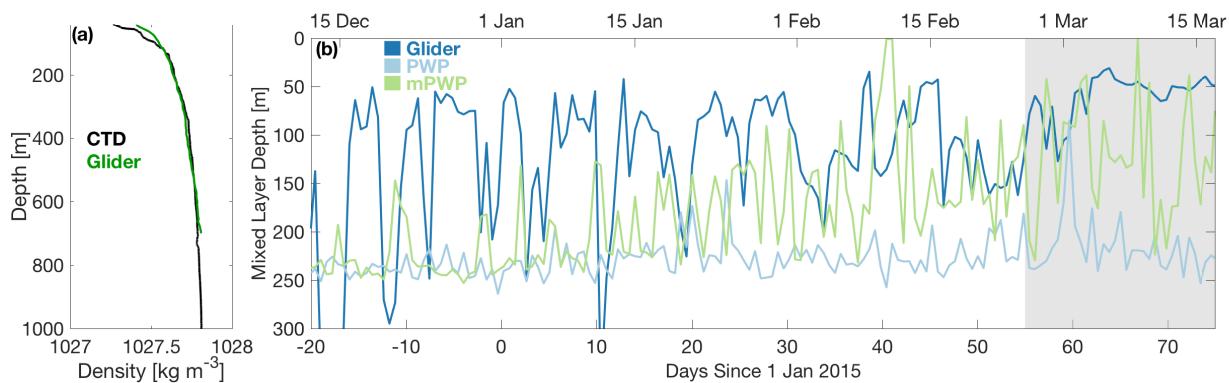
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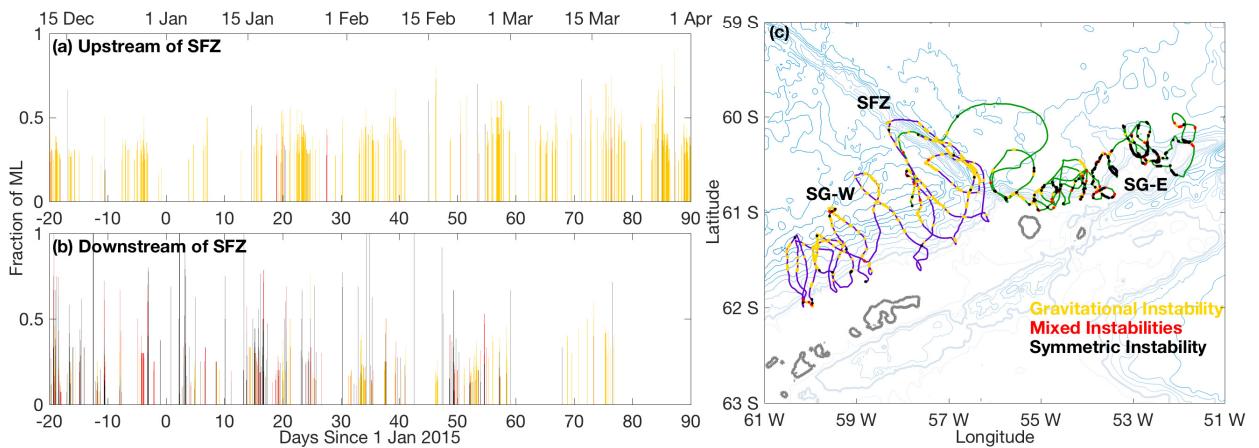
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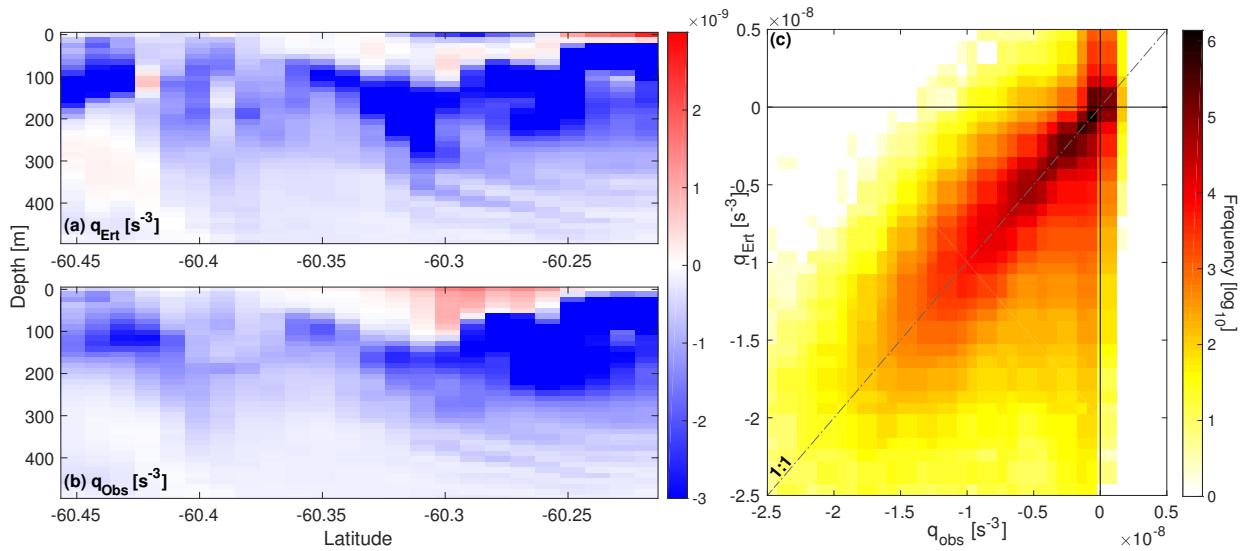
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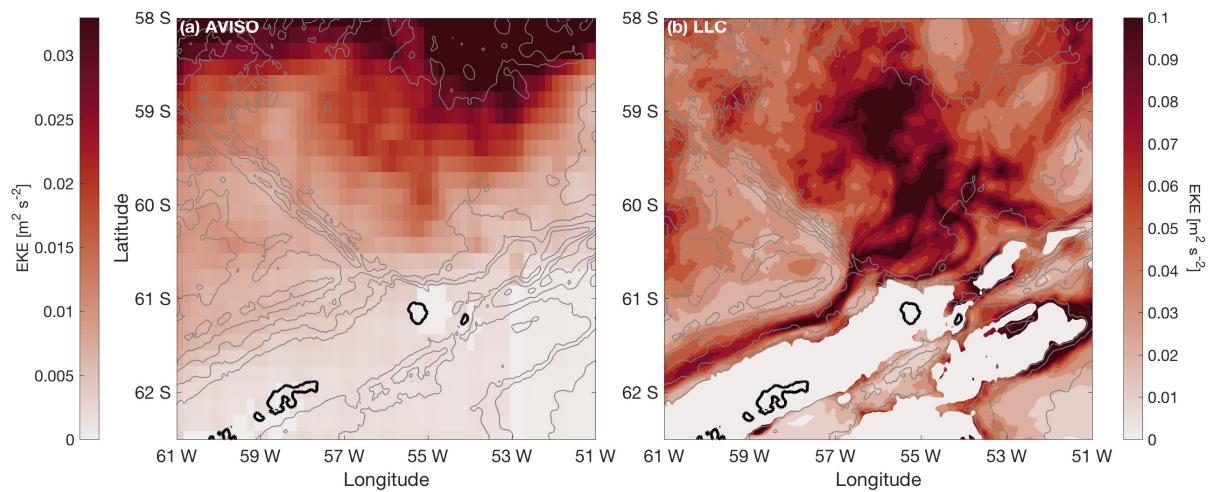
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