

IMPACT OF CLOUD AND RAIN EVENTS ON SARAL/ALTIKA MEASUREMENTS

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Summary

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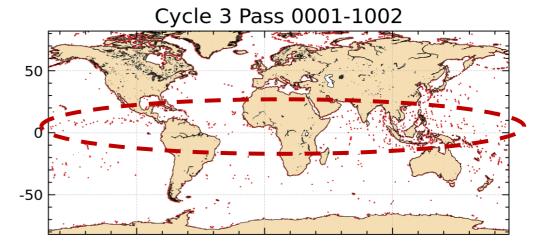


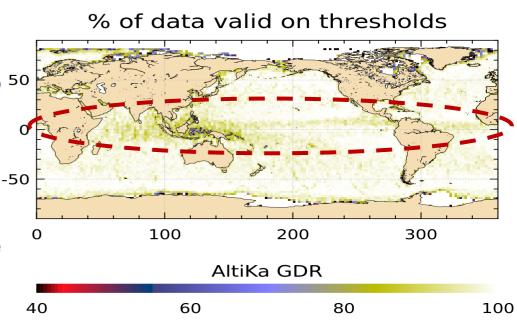




AltiKa characteristics

- AltiKa is a mono frequency altimeter, operating in Ka-band which is strongly affected by the presence of atmospheric water.
- The altimeter acquires data 96 % of the time (all surfaces combined)
- Rate of data lost due to rain over ocean
 is lower than anticipated < 0.1% thanks to 50
 margins into the link budget.
- The % of edited data on thresholds (as mentioned in the handbook products) is more important in low latitudes mainly due to rain cells





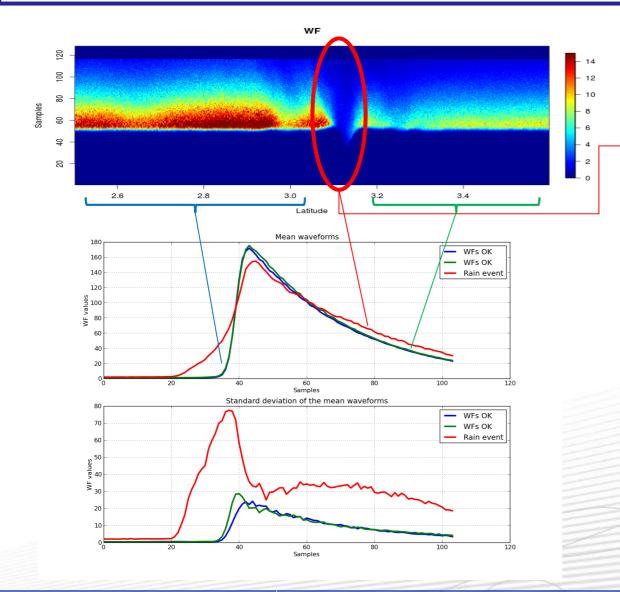








Impact of rain on AltiKa waveforms



Rain event induce strong attenuation of the waveforms

But also fast temporal variations of the shape of echoes

→ All geophysical estimates are impacted









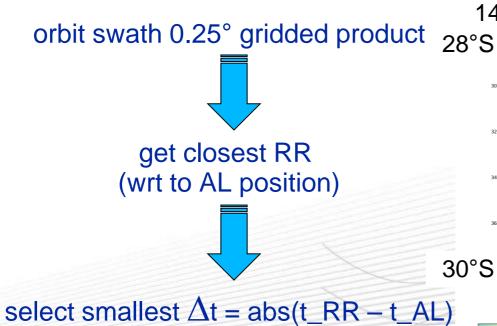
Collocation with SSMI and WindSat rain rate measurements







Get Rain Rate for AltiKa from external sources



(among the external sources)

144°W
28°S
RR = 25
200
175
30°S
WINDSAT
NOTE: The second of the second o





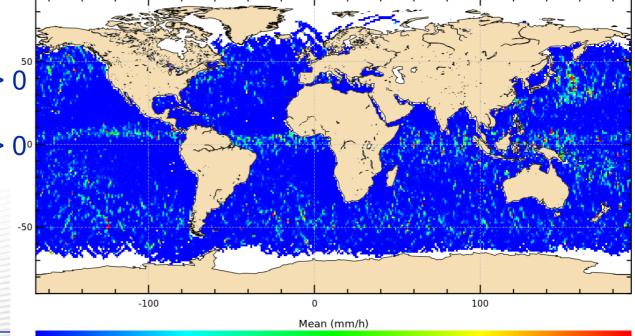
AltiKa verification meeting: India 22-24 April 2014





Towards a radiometer rain rate product for AltiKa

- Rain for AltiKa combined :
 - RR [mm/hr]
 - → ~ 80 % of AL measurement are covered
 - → including 10% of RR > 0
 - Confidence Flag (based on LWC and TB@37)
 - → ~ 70% of RR > 0 are considered effective rain events
 - $\bullet \Delta t = abs(t_RR t_AL)$
 - → ~ 80% of "true" RR > 0 with Δt < 60 min
 - \rightarrow ~ 10% of "true" RR > 0° with Δt < 10 min
- → will be used as a learning dataset for an integrated product







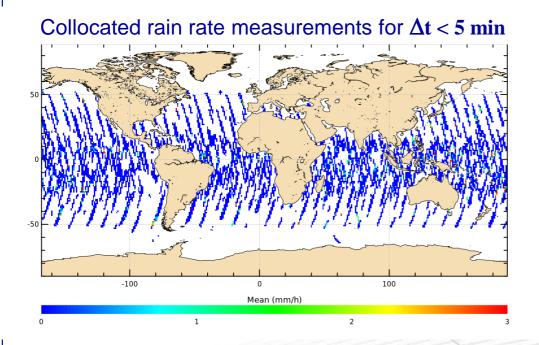


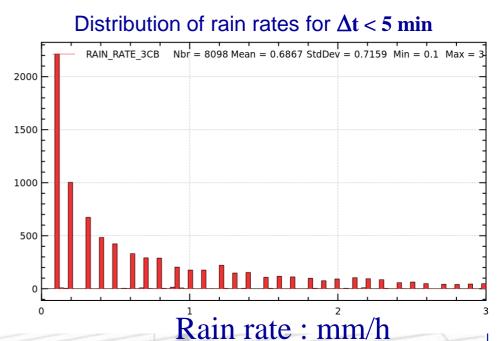




Impact of rain rate on AltiKa geophysical estimates

• As rain cells can appear, move and disappear very quickly, we select collocated data with a $\Delta t < 5$ min to look at the impact of the rain rate on the geophysical parameters estimated from AltiKa waveforms





As expected, most rain events are weak (less than 3 mm/h)

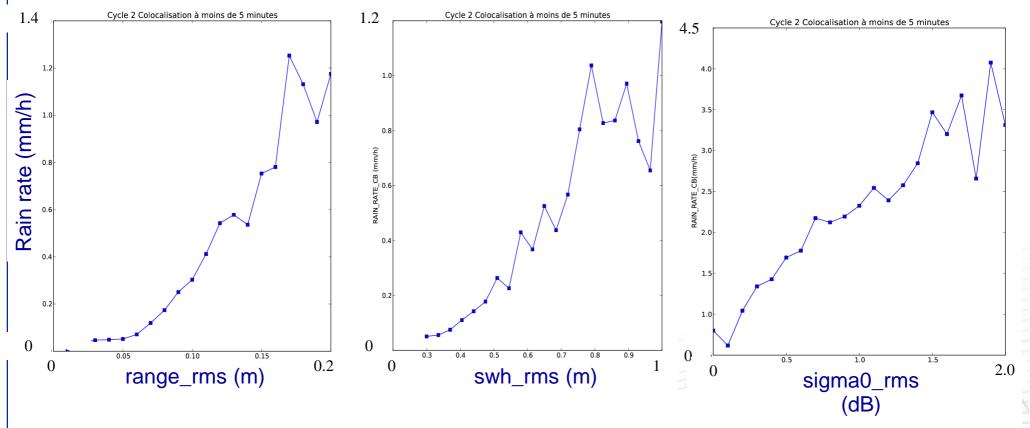








Impact of rain rate on AltiKa geophysical estimates



- Rain cells strongly increase the noise on range, swh and sigma0.
- The impact of rain rates is more important on the sigma0
- Relation between rain rate and range_rms/swh_rms is not linear

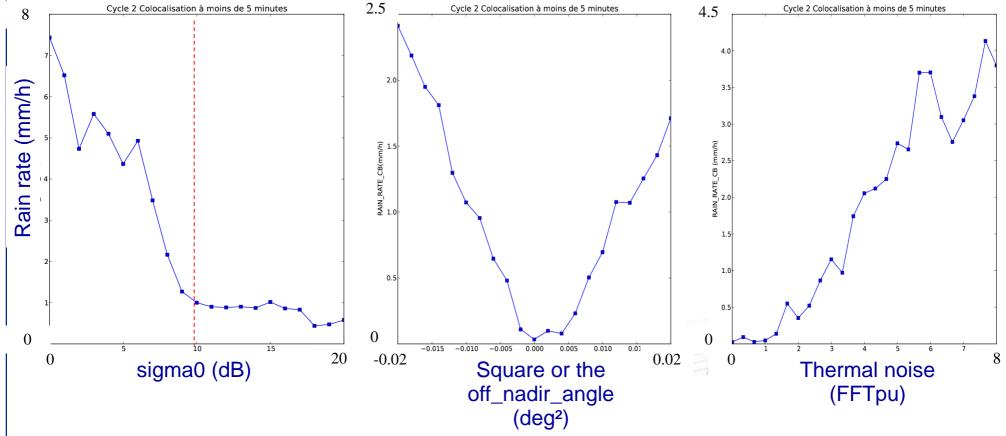








Impact of rain rate on AltiKa geophysical estimates



- As expected: strong attenuation of the sigma0
- Strong impact on the square of the off_nadir_angle and the thermal noise
 - → the high sensitivity of those 2 parameters can be exploited



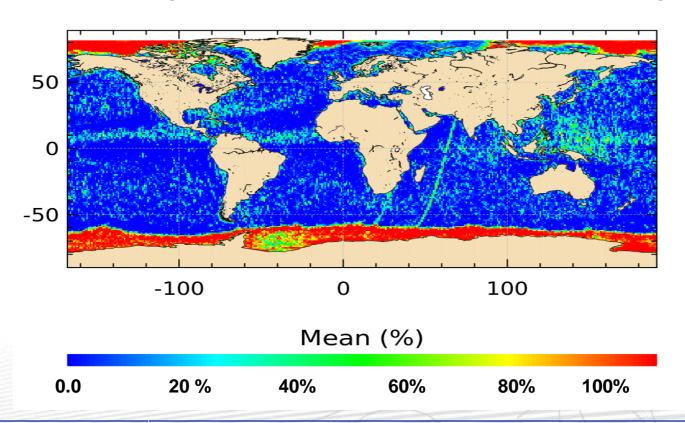






Detection of measurements impacted by rain: Matching Pursuit

- The Matching Pursuit algorithm was developed by J. Tournadre to detect quick and strong temporal variations of the slope of the waveform trailing edge
- Combined with the 1Hz radiometer liquid water content, it can be a good processing to identify altimeter measurements impacted by rain at 1Hz
- Since patch 2, this flag (available in AltiKa GDR products) provides good detection



~ 10% of data are identified on ocean between lat +/- 50°



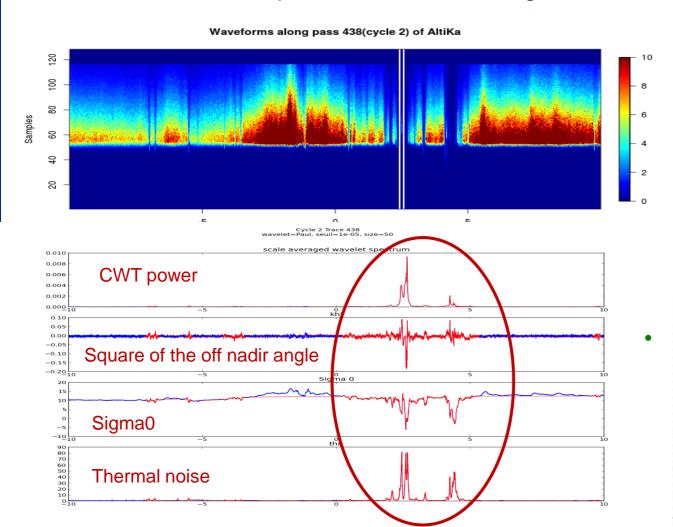




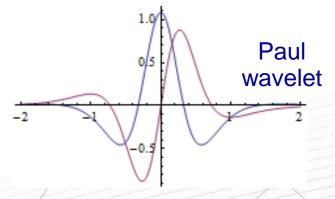


Detection of measurements impacted by rain: CWT

 Another relevant detection method consists in computing a Continuous Wavelet Transform on the square of the off nadir angle derived from the waveform.



$$W_n(s) = \sum_{n'=0}^{N-1} x_{n'} \psi^* \left(\frac{(n'-n)\delta t}{s} \right)$$



Combined with the thermal noise level, the CWT is a powerful processing to identify geophysical phenomena on altimeter measurements like rain events







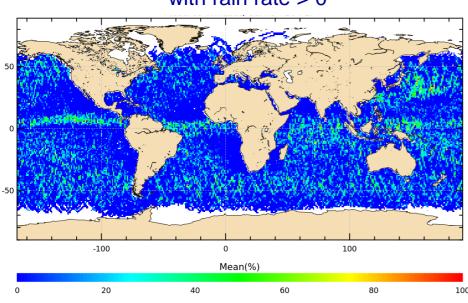




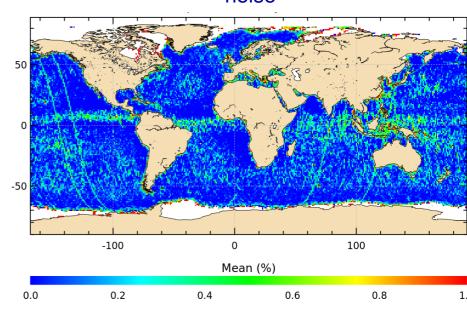
Continuous Wavelet Transform

- The combination of CWT and threshold on thermal noise identifies ~ 10% of 40Hz data
- SSMI and WindSat measurements provides ~ 9.6 % of rain rates > 0
 - → Good agreement between measurements and the CWT detection





% of flagged data by the CWT + Thermal noise











Conclusions

- Even if the Ka-band is very sensitive to the presence of atmospheric water, data lost **is lower than expected** thanks to margins in the link budget.
- □ However, waveforms and thus all geophysical estimates derived from WF are impacted by rain events → the slope of the trailing edge and the thermal noise parameters can be used to detect rain events.
- Several methods to detect rain events exist: The Matching Pursuit algorithm provides good 1Hz rain flag when combined with the radiometer liquid water content and is available in AltiKa products.
- A powerful detection algorithm is constructed from the combination of the CWT applied on the slope of the trailing edge and a thermal noise threshold.
 - → Results are in agreement with the radiometer measurements (colocalized) and can be directly used at 40Hz to edit data polluted by rain events
- Both algorithms estimate that ~10% of AltiKa measurements are affected by rain in deep ocean.









Thank you for your attention





