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1           **Examining the impact of surface currents on satellite**  
2                           **scatterometer and altimeter ocean winds**

3           AMANDA M. PLAGGE \* AND DOUGLAS VANDEMARK

*University of New Hampshire, Durham, NH*

4                           BERTRAND CHAPRON

*IFREMER, Brest, France*

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\* *Corresponding author address:* Amanda Plagge, Ocean Process Analysis Lab at the University of New Hampshire, 8 College Rd, Durham, NH 03824.

E-mail: amanda.plagge@unh.edu

## ABSTRACT

5

6 A five-year dataset collected over two surface current and meteorological moorings allows rig-  
7 orous evaluation of questions surrounding wave/current interaction and the scatterometer.  
8 Results demonstrate that scatterometer winds represent winds relative to the moving sea  
9 surface, affirming previous observational efforts that inferred the phenomenon using clima-  
10 tological approaches over larger time and space scales in equatorial and Western boundary  
11 currents. Comparisons of wind residuals between Ku-band QuikSCAT and buoy measure-  
12 ments show near one-to-one correlation with ocean surface velocity for 5, 12.5, and 25 km  
13 resolution wind speed products, especially under conditions of moderate wind speed and  
14 near-neutral atmospheric stability. Scatterometer and buoy wind direction differences due  
15 to currents were observed to be negligible for the range of surface velocities encountered and  
16 the length scales observed by QuikSCAT. Similar analyses are applied to C-band ASCAT  
17 satellite wind measurements at the same sites as well as to satellite altimeter winds, and  
18 overall confirm the results seen with QuikSCAT; differences are likely the combined result  
19 of sampling, satellite wind algorithms, and geophysical wind-wave coupling in the presence  
20 of currents. On the whole, this study affirms that at length scales of 10 km and longer the  
21 scatterometer wind can be considered to be current-relative. Observed differences between  
22 earth-relative and current-relative wind of order 10-20% of the wind velocity are not un-  
23 common in this and other ocean regions and this study more fully validates that microwave  
24 remote sensing winds appear to respond to wind stress even in the presence of larger scale  
25 currents

# 1. Introduction

The ever-increasing number of surface current measurements across the world's oceans is leading to renewed appreciation for the role that surface currents play in atmosphere-ocean dynamics. These observations, from drifters, gliders, profilers, and satellites within the global ocean observing system, present a next challenge - the incorporation of a fluid air-sea boundary condition into atmosphere-ocean coupling, with impacts both upon wind stress at the sea surface and the resulting ocean circulation (Kara et al. (2007)) as well as atmospheric boundary layer modifications (Chelton et al. (2004), O'Neill et al. (2005), Chelton et al. (2006)). As part of these issues, there is increased recognition of the fundamental effect of surface currents on near-surface wind speeds derived using satellite microwave systems. Winds inferred using these sensors rely on changes in surface backscatter or emission tied to the geometrical roughness changes driven by surface wind waves. In the presence of currents, waves will grow with the effective wind, leading many to directly interpret satellite winds as a wind stress or a current-relative wind, rather than one that is relative to the fixed earth reference. While intuitive, supporting evidence for this premise remains limited (Dickinson et al. (2001), Quilfen et al. (2001), Chelton et al. (2004), Kelly et al. (2005)) in large part because the effect is typically small with respect to the mean wind and because measurement approaches to quantitatively isolate the effect require an exacting approach. This study presents an attempt to more fully demonstrate surface current impacts within the context of satellite scatterometer ocean wind measurements.

Satellite scatterometry is the most widely applied approach for the global measurement of near-surface ocean wind speed and direction. The measurement principle involves radar detection of surface gravity and gravity-capillary wave changes that primarily reflect the winds observed near the air-sea interface (cf. Donelan and Pierson (1987)). The complexity across multiple geophysical problems involved in analytically relating radar backscatter to waves and then to wind stress is daunting and, to date, the method for inverting wind vector

53 data from radar observations is an empirical model function developed to relate *in situ* wind  
54 measurements to radar backscatter. This approach is mature (e.g. Stoffelen and Anderson  
55 (1997), Freilich and Dunbar (1999), Ebuchi et al. (2002), Tang et al. (2004), Hersbach et al.  
56 (2007), Bentamy et al. (2008), Hersbach (2010)) and leads to global scatterometer wind  
57 products with accuracy of better than  $1.2 \text{ m s}^{-1}$  and 10 degrees. However, scatterometry  
58 still has several issues to resolve or constrain if long-term, uniform, and climate-relevant  
59 wind vector data are to be produced. First, the satellite sensor community operates several  
60 different scatterometers with varying probing wavelengths (L, C, and Ku-band) and viewing  
61 geometries; thus a separate empirical model function is required in each case along with  
62 subsequent cross-platform consistency evaluations. Another issue is due to the fact that  
63 the scatterometer wind is derived from ocean wind waves and not the earth-relative wind  
64 itself. This point has led many to assume the scatterometer is a more closely akin to a  
65 wind stress measurement system (e.g. Weissman and Graber (1999)). Yet, existing em-  
66 pirical scatterometer wind stress models or data products are limited, primarily because of  
67 the paucity of direct *in situ* wind stress observations, such as direct covariance flux estimates.

68

69 Using Monin-Obukhov similarity theory, the standard approximation relating the stress  
70 to the wind for the scatterometer is written in terms of a neutral atmospheric stability  
71 and current-relative wind vector at 10 m above the ocean (Liu and Tang (1996), Bourassa  
72 (2006)):

$$73 \quad \mathbf{U}_{10N} = \mathbf{U}_s + \frac{\mathbf{u}_{*a}}{\kappa} \ln z/z_0 \quad (1)$$

74 Here, the parameter  $\kappa$  is von K arman’s constant,  $\mathbf{u}_{*a}$  is the friction velocity, and the term  
75  $\ln z/z_0$  refers to the approximately logarithmic increase in wind speed with height. This  
76 term depends not only on altitude above the surface ( $z$ , here 10 m) but on the properties  
77 of the surface (roughness length,  $z_0$ ). The left-hand side of the equation can be derived  
78 in terms of measured scalars to yield a bulk  $\mathbf{U}_{10N}$ ; this is the usual means of developing  
79 a scatterometer wind vector geophysical model function (GMF). The term  $\mathbf{U}_s$ , the surface

80 ocean current vector, is an additive term that assumes that currents dictate a fluid bottom  
81 boundary condition but do not impact, for example the roughness length  $z_0$ .

82

83 Numerous past field and wave tank experiments (e.g. Plant (1977), Moore and Fung  
84 (1979), and Donelan and Pierson (1987)) have shown that radar backscatter is primarily  
85 induced by shorter gravity-capillary waves of order 1-20 cm. However, it is also known that  
86 different wave scales respond differently to changes due to atmosphere-ocean coupling at-  
87 tributed to all ocean and atmospheric boundary layer dynamics but specifically reflective  
88 of atmospheric stability, frontal gradients in either fluid, longer gravity waves in the range  
89 from seas to swell, and wave-current interactions (Phillips (1977)). Do all scatterometer  
90 model functions (the right-hand side of Eq. 1) yield the same  $\mathbf{U}_{10N}$  and, more to the point,  
91 do C-band and Ku-band systems yield the same results for various geophysical conditions  
92 at the air-sea interface? In this paper we attempt to observationally address the following  
93 questions: does the kinematic boundary condition hold for the pertinent wavelengths (i.e.  
94 do the applicable wind waves grow the same in and out of regions with a moving ocean)?  
95 Is this the same for Ku-band sensors as for C-band? At what length and time scales is  
96 this true? The answers to these questions are crucial for several reasons. First, because  
97 synthetic aperture radar (SAR) wave/current studies have shown differences at Ku- and  
98 C-band (Lyzenga (1998), Johannessen et al. (2005), Kudryavtsev et al. (2005), Marmorino  
99 et al. (2011)). Next, because surface currents become more important as scatterometer ap-  
100 plications are expanded and refined. These applications include but are not limited to (1)  
101 climate records, (2) fine-scale evaluations of air-sea coupling over frontal adjustment zones  
102 (eddies, the ITCZ, and western boundary currents), (3) assimilation of scatterometer winds  
103 into surface current products in regions with persistent strong currents such as the equatorial  
104 Pacific, and (4) any use of scatterometer winds in coastal regions with strong and highly  
105 dynamic currents.

106

107 The few observational studies addressing the effects of surface currents on scatterometer  
108 wind retrievals focus mostly in the equatorial region, where strong wave-current and air-sea  
109 interactions appear to complicate the relationship, and where only climatological or sub-  
110 surface ocean current estimates have been used. For these reasons, many of the questions  
111 above remain. In their 2005 paper, Kelly et al. show good agreement between zonal col-  
112 located wind differences and climatological zonal currents for Tropical Atmosphere Ocean  
113 (TAO) buoys and QuikSCAT (Kelly et al. (2005)). An earlier study by Quilfen et al. also  
114 shows a measurable but weak correlation between C-band scatterometer wind residuals and  
115 measured current at 10 meters depth on two TAO buoys (Quilfen et al. (2001)). However,  
116 both of these studies note that it is difficult to quantify the effect in part due to the lack  
117 of sufficient surface current measurements; additionally, the study of Kelly et al. (2005) was  
118 unable to find an expected relationship between meridional wind residuals and currents. As  
119 part of a comprehensive study of QuikSCAT wind vector accuracy at ocean buoys including  
120 TAO and various National Data Buoy Center (NDBC) buoys, Ebuchi et al. (2002) attempted  
121 to explain the differences between QuikSCAT and buoy winds by correlating the wind speed  
122 residuals with both sea surface temperature (SST) and air-sea temperature difference. They  
123 suggested that the very low correlations that resulted might be due to neglecting the effects  
124 of surface currents; but their attempt to remove the current effects by repeating the study  
125 using only NDBC buoys outside the strong currents of the equatorial region produced cor-  
126 relations that were just as low.

127

128 Accordingly, our approach is to gain a larger sampling of data and range of surface and  
129 wind conditions by using a coastal region with a large diurnal reversing current and an ex-  
130 tensive *in situ* near-surface current measurement record. We investigate the effects of surface  
131 currents on collocated scatterometer retrievals at both Ku- and C-band, and with a data  
132 sample population large enough to permit filtering to ameliorate competing factors such as  
133 atmospheric stability and sea state. We include assessment of current impacts on satellite

134 altimeter winds (cf. Vandemark et al. (1997)) for the same sites in order to infer if a broader  
135 portion of the ocean wave spectrum responds in a manner similar to that for the waves  
136 controlling the scatterometer signal.

137

## 138 2. Data and Methods

139 The study site is the eastern Gulf of Maine centered about buoys N and L as noted in  
140 Fig. 1 - a location selected for several reasons. First, the region is known for strong reversing  
141 semidiurnal (M2) tides (Bigelow (1927), Dupont et al. (2003)) that lead to a local daily vari-  
142 ation in surface currents upwards of  $-0.3$  to  $0.3$  m s<sup>-1</sup>. The tides, combined with wind driven  
143 and bathymetrically controlled coastal currents, provide a large dynamic range in the mean  
144 flow bottom boundary condition for air-sea interaction and an average near-surface current  
145 velocity of about 40 cm s<sup>-1</sup> (Fig. 2) at both buoys L and N. The second feature of the site  
146 is the long-term hourly record of both ocean currents and surface wind vector measured at  
147 these two buoys during a period of twice-daily satellite scatterometer passes that extends  
148 from 2004-2011 for Buoy N and 2003-2008 for Buoy L. Moreover, QuikSCAT scatterome-  
149 ter wind vector measurements at multiple resolutions were recently validated in this region  
150 (Plagge et al. (2009)) and thus the mean agreement between QuikSCAT and *in situ* winds  
151 for this site is well established. It should also be mentioned that buoys L and N are both in  
152 coastal waters, with a distance from shore of 37 and 120 km respectively. While land con-  
153 tamination can, at times, bias scatterometer wind vector data (cf. Tang et al. (2004); Plagge  
154 et al. (2009)), these impacts are typically seen for data within 14-80 km from shore. Despite  
155 buoy L being nearer to land than buoy N, Plagge et al. (2009) was able to affirm that for  
156 both buoy sites, QuikSCAT data are not contaminated by land effects. A final observation  
157 regarding the site concerns the spatial length scales associated with the surface currents at  
158 the two buoys. Buoy N is moored within the Northeast Channel, a region of deep water

159 exchange for the Gulf of Maine while buoy L is located north of Browns Bank and inflow  
160 from the coastal Scotian current (Smith et al. (2001)). In both cases, local bathymetry and  
161 the forcing lead to spatial variability in currents of  $O(20-40 \text{ km})$  (e.g. Manning et al. (2009)).  
162 This issue will be addressed later in the study.

163

164 Buoy near-surface currents are measured using an Aanderraa model RCM 9 current me-  
165 ter with an accuracy of  $0.15 \text{ cm s}^{-1}$  or 1% of the reading and operated at 2 m depth, close  
166 enough to the surface to minimize the effects of shear with depth. Winds are measured using  
167 RM Young or Vaisala Windsonic anemometers with an accuracy of  $0.3 \text{ m s}^{-1}$  with 8-minute  
168 averaged winds every hour and obtained via the National Data Buoy Center (Buoy N and L  
169 are NDBC stations 44024 and 44038 and are owned and operated by the Univ. of Maine).  
170 Ancillary buoy measurements also utilized in this study are air and sea surface temperature,  
171 relative humidity, atmospheric pressure and ocean significant wave height. To compare with  
172 scatterometer winds, the buoy wind measurements are adjusted to provide a 10-m neutral  
173 stability wind estimate using the COARE 3.0 bulk flux algorithm (Fairall et al. (2003)). All  
174 wind data from this point forward are 10-m neutral winds. Fig. 3 provides the distribution  
175 of buoy-observed directions for the wind and surface current at both buoy locations within  
176 the total co-registered scatterometer/buoy database. The north-south (northwest-southeast)  
177 orientation of the M2 tidal ellipse for buoy L (N) is apparent in the surface current record,  
178 as distinguished by the twin peaks in both solid lines in Fig. 3a. The directional difference  
179 between the wind and current vector is also shown and it is clear that a fairly uniform distri-  
180 bution between wind and current vectors is observed. As expected, this site yields a data set  
181 with a wider range of wind-current conditions than found for equatorial regions with their  
182 more persistent winds and currents (Quilfen et al. (2001); Kelly et al. (2005)).

183

184 The primary scatterometer wind data for this study come from the QuikSCAT satellite  
185 Ku-band scatterometer and we evaluate data provided for three spatial resolutions: 25 km

186 (L2B product from NASA-JPL’s Physical Oceanography Distributed Active Archive Cen-  
187 ter (PODAAC)), 12.5 km (L2B, PODAAC), and 3-5 km (provided by Dr. David Long of  
188 Brigham Young University). The latter are referred to as ultra-high resolution (UHR) data  
189 (Owen et al. (2003)). Because regional surface current structures are of a finite spatial scale,  
190 it was desirable to examine all three data products to assess the potential impact of footprint  
191 size in this current impacts investigation. Although UHR data are still considered experi-  
192 mental, they have previously been validated in the Gulf of Maine (Plagge et al. (2009)). To  
193 summarize the validation, UHR-buoy residuals are comparable with standard QuikSCAT  
194 products, with a slight increase in directional noise but additionally increased spatial en-  
195 hancement of frontal features. The selected wind vector cell (WVC) solution for each cell is  
196 the most likely choice as given by the Direction Interval Retrieval with Threshold Nudging  
197 (commonly called DIRTH) algorithm, described in the user handbook (Dunbar et al. (2006)).

198

199 The process for collocating *in situ* and QuikSCAT data both spatially and temporally is  
200 documented in previous work (Plagge et al. (2009)). Briefly, collocated wind observations  
201 between buoy and scatterometer must occur within thirty minutes (buoy-based current and  
202 wind measurements are effectively coincident). For every pass within the time frame of a  
203 given buoy/scatterometer match, all scatterometer wind vector cells within a 10 km radius  
204 of the buoy have been averaged to provide the average wind speed and direction for each  
205 resolution. This process provides a total of 4739 triplet matches (scatterometer, buoy wind,  
206 and current data) for the UHR, 3996 matches for the 12.5 km, and 2250 matches for the  
207 25 km product. It should be noted that during previous investigations (i.e. Plagge et al.  
208 (2009)), this type of collocation (using the average within a given radius) was compared  
209 with “nearest neighbor” collocation in this region and with these buoys, with no significant  
210 difference between the resultant scatterometer-buoy residuals. Additionally, although each  
211 product has a different number of triplet collocations, using only points where all three  
212 product triplets are available produces results that are statistically invariant compared to

213 using all available data. Therefore the dataset retains all possible triplets, meaning there  
214 are instances where, for instance, only the UHR product has a collocation.

215

216 As discussed in Ebuchi et al. (2002) it is important to consider and address data qual-  
217 ity flagging and scatterometer wind vector ambiguity selection in any detailed analysis of  
218 wind residuals. Several pre-filtering steps are taken prior to analyses. For all scatterometer  
219 products, and before collocation, any wind vector cell estimate flagged as occurring during  
220 rain is rejected. Next, any triplet where any wind speed lies above  $18 \text{ m s}^{-1}$  or where the  
221 current magnitude lies outside of three standard deviations of the overall mean current for  
222 the dataset are rejected to exclude infrequent extreme event data. Finally, cases where the  
223 scatterometer direction estimate lies beyond 45 deg. from the buoy are rejected as being  
224 cases of poor WVC ambiguity selection. After these latter quality control steps, 3627 UHR  
225 triplets, 3250 12.5 km triplets, and 1862 25 km triplets remain. Overall, the results of fol-  
226 lowing analyses with and without such filtering are statistically similar excepting slightly  
227 improved linear correlation coefficients.

228

229 Comparison of QuikSCAT and buoy wind speeds from the resulting data set are shown  
230 in Fig. 4 for each resolution and buoy with the linear correlation coefficient and a linear  
231 least-square regression fit between the data shown in each panel. The level of agreement  
232 between satellite and *in situ* data is consistent with that obtained in the previously cited  
233 studies in terms of standard deviation and bias, although one does observe a systematic scat-  
234 terometer wind overestimation above  $12\text{-}15 \text{ m s}^{-1}$  in all three products and at both buoys,  
235 an observation also noted in previous work in the Gulf of Maine (Plagge et al. (2009)).

236

237 Our approach to a broader assessment of current impacts on satellite microwave sensor  
238 winds at this site entails performing similar matchup comparisons and analyses of C-band  
239 scatterometer and Ku-band satellite altimeter data, following on from earlier studies that

240 worked with much smaller data sets (Quilfen et al. (2001), Vandemark et al. (1997)). The  
241 first additional matchup datasets contain measurements from the Advanced Scatterometer  
242 (ASCAT) sensor, operated by EUMETSAT as part of the Metop-A platform. ASCAT oper-  
243 ates at a C-band frequency, and standard data products are provided at 25 km and 12.5 km  
244 resolution since 1 Nov. 2007 (EUMETSAT (2011)). Bentamy et al. (2008) indicates that  
245 ASCAT winds are comparable to QuikSCAT winds globally, and have similar root-mean-  
246 squared differences when compared with buoy data ( $1.72 \text{ m s}^{-1}$  and  $18^\circ$ ). Since Sept. 2010,  
247 a newer type of ASCAT wind vector retrieval, cited as the coastal product, also provides  
248 12.5 km resolution data but utilizes a different processing method than the standard AS-  
249 CAT products (Verhoef and Stoffelen (2011)). The main difference between the standard  
250 and coastal processing is that the former uses a Hamming window, while the latter is a  
251 simple rectangular (“box”) window. The validation report for the coastal product notes  
252 that the box-averaged product may potentially experience lower geophysical noise than the  
253 Hamming-window product (Verhoef and Stoffelen (2011)); this possibility will be discussed  
254 further in a later section. Due to the shorter ASCAT data record and swath coverage dif-  
255 ferences, there are fewer triplets for the ASCAT match-ups: 836 triplets for the 12.5 km  
256 product, 941 for the 25 km product, and 138 for the coastal product after quality control.  
257 For satellite ocean altimetry, we collocate wind speed estimates obtained using three sep-  
258 arate Ku-band altimeters: Jason-1, Jason-2, and Envisat, using project Geophysical Data  
259 Records as extracted from the Radar Altimetry Database System (Scharroo (2008)). Note  
260 that the nominal spatial resolution for the altimeter is 6 km, inherently a finer spatial scale,  
261 and thus less error due to spatial smoothing should be obtained. Any measurements within  
262 a 15 km radius of buoy N were averaged, yielding 388 total collocated triplets over the period  
263 2004-present. It should also be noted that due to differing satellite tracks, neither ASCAT  
264 nor the altimeters were able to provide collocations with buoy L.

265

### 3. Results

Analyses in this study are focused on isolating the current impact on scatterometer  $U_{10N}$  explicit in Eq. 1. First, we assume that wind speed residuals between a microwave satellite wind and the fixed earth reference mooring wind measurement relates to  $\mathbf{U}_s$  in this equation. Given the model in Eq. 1, we assume that it is only the component of the current vector in the direction of the wind that will contribute to a difference between a scatterometer-retrieved (stress-based) wind vector and a wind vector measured by an anemometer. Therefore, in this study we will examine the residual against an effective surface velocity ( $u_p$ ) where the relevant surface velocity is the vector component projected onto the buoy's wind direction ( $\theta_{wind}$ ) and defined as

$$u_p = |\mathbf{U}_s| * \cos(\theta_s - \theta_{wind}), \quad (2)$$

where  $|\mathbf{U}_s|$  is the surface current magnitude and  $\theta_s$  is the direction of the current in meteorological convention.

This approach differs somewhat from past field studies that separately address mostly zonal wind and current components within sites having well defined large scale currents (Quilfen et al. (2001), Kelly et al. (2005)) along these axes. By using  $u_p$ , all possible combinations of wind and current directions are enfolded in a single statistical assessment. The inclusion of all conditions should allow us to best capture large currents associated with local wind and circulation beyond just the tidal flow (Smith et al. (2003)), but may also lead to a higher level of non-current induced variability in the wind residual due to the range of other processes and conditions that can affect wind residual assessment in the coastal zone (Freilich and Dunbar (1999), Plagge et al. (2009), Portabella and Stoffelen (2009)), such as orographic effects on wind, multi-scale weather patterns, changing fetch, strong air-sea temperature differences, and breaking waves.

292 Before proceeding, we also examined the implicit assumption that scatterometer wind  
293 direction estimates are invariant with respect to the buoy wind under the observed range  
294 of current vectors. This assumption is made in our progression from Eq. 1 to Eq. 2; if  
295 a surface current normal to the wind would cause a bias in the direction retrieved from  
296 the scatterometer, the use of Eq. 2 would be limited or confusing. However, investigation  
297 showed no significant bias in scatterometer direction related to currents. For our dataset, no  
298 angular difference (i.e.,  $\theta_s - \theta_{wind}$ ) sector exhibited biases greater than 6 degrees. Therefore  
299 using speed or wind vector differences yield nearly equivalent results and the focus is solely  
300 on wind speed versus the wind-projected current going forward..

301

302 QuikSCAT wind residuals versus  $u_p$  for all data contained in the pre-filtered matchup  
303 data sets at both buoys (L and N) are presented in Fig. 5. A separate panel is shown for  
304 each of the three Ku-band scatterometer products. Positive (negative)  $u_p$  indicates that the  
305 projected current and wind are aligned in the same (opposite) direction. The data scatter  
306 about zero with an rms of nearly  $2 \text{ m s}^{-1}$ . Most importantly, there is a clear, though small,  
307 negative correlation evident in the data indicating the scatterometer wind exceeds the buoy  
308 in the event of an opposing current. Noted linear regression fit parameters are similar for  
309 all three resolutions and show slopes of -0.8 to -0.9 highlighted with the grey dashed line in  
310 each panel. The linear correlation ( $R$ ) coefficients are quite similar (-0.185 (UHR), -0.161  
311 (12.5 km), and -0.166 (25 km)) and the 95% confidence interval for  $R$  lies above -0.12 for all  
312 three cases.

313

314 Fig. 6 also presents the same data after bin-averaging versus  $u_p$ , with a change in the y  
315 axis to accentuate the 1:1 anticorrelation with currents that is expected if the scatterometer  
316 residuals are indeed current-relative. The black-dashed line shows this ideal slope of -1. A  
317 weighted linear least-squares model is applied to the binned data, using the inverse of each  
318 bin's standard error as the weights (Bevington and Robinson (1992)); the resultant linear fit

319 is plotted as a gray dash-dot line and shown as an equation on Fig. 6. Only bins containing  
320 at least 10 points contribute to the fit, to satisfy the central limit theorem. A histogram of  
321 samples in each bin is shown as a grey solid line. Fit coefficients and their uncertainty are  
322 provided on each panel. To within the confidence intervals given, these slope estimates agree  
323 with those from the unweighted slope values given in Fig. 5 for each QuikSCAT resolution.  
324 Again, each QuikSCAT product yields a similar result of a negative slope lying between -0.82  
325 and -0.85. Also note that the significance level of the wind residual relationship versus  $u_p$   
326 is evident from the error bars, extending out to a range of  $u_p$  of -0.6 to 0.6 m s<sup>-1</sup>. While  
327 the figures show combined results for buoys L and N, those for the individual buoys were  
328 similar. All weighted fit parameters are provided in Table 1.

329

330 While these initial results show a clear correlation between speed residuals and  $u_p$  and a  
331 slope of nearly -1, the correlation coefficient values fall well below the levels of 0.4 to 0.6 cited  
332 in past field scatterometer studies (Kelly et al. (2001), Quilfen et al. (2001)). This evaluation  
333 includes all data collected without consideration for varied sea state and air-sea conditions.  
334 As noted in the introduction, detecting and reducing spurious correlation amongst factors  
335 (waves, atmospheric stability, currents, geophysical model function errors) controlling the  
336 scatterometer winds at the 1-2 m s<sup>-1</sup> level is difficult. As one example, consider the possible  
337 case where stable atmospheric conditions systematically bias the scatterometer winds low  
338 and also regularly coincide with positive  $u_p$  in our region. This would negate or ameliorate  
339 the current impact depending on the covariance between these effects. To investigate whether  
340 current impacts can be more clearly resolved, we computed the aforementioned statistics af-  
341 ter filtering by differing wind, wave, and atmospheric stability regimes (cf. Ebuchi et al.  
342 (2002)). Results, including linear correlation coefficients, are given in Table 2. Slopes and  
343 correlations are not significantly different across the table for varied scatterometer resolu-  
344 tions.

345

346 In general, the best results are seen for moderate winds, low sea states ( $<1.6$  m) and  
347 near neutral stability. This region does not experience a wide range of wave conditions  
348 and thus wave impacts are unlikely to be a large factor in the results of this study. But  
349 increased noise and/or bias in scatterometer-buoy wind comparisons at low winds, due in  
350 part to the variability of the wind field at these speeds (Plagge et al. (2009), Ebuchi et al.  
351 (2002), Kelly et al. (2005)), and to strongly stable or unstable boundary layer conditions  
352 are likely contributors to the weaker correlations and lower or higher slopes. The variation  
353 in regression slopes and correlation values is considered to be combined geophysical and  
354 statistical effects more than an actual increased or decreased dependence on surface current.  
355 From numerous past studies addressing conditions associated with best agreement between  
356 scatterometer and buoy winds, it is reasonable to assume that the best geophysical condi-  
357 tions to focus on surface current impact assessments are those of near-neutral atmospheric  
358 stability ( $-0.4 \leq z/L \leq 0.1$ ) and moderate wind speeds of  $5-10$  m s<sup>-1</sup>. Under those filtering  
359 conditions, we achieve correlations of  $-0.250$  (UHR),  $-0.256$  (12.5 km) and  $-0.266$  (25 km)  
360 with the bin-averaged results shown in Fig. 7. By contrast, the conditions that yield the  
361 weakest correlation are those for light winds and unstable boundary layers ( $z/L < -0.4$ ).  
362 In this case, the relationship is far from  $-1:1$  for all resolutions (Fig. 8), and the correlations  
363 quite low:  $-0.122$  (UHR),  $-0.071$  (12.5 km), and  $-0.116$  (25 km).

364

365 Results from a similar evaluation of C-band ASCAT satellite scatterometer data are  
366 shown in Figs. 9 and 10. The lower data sample size is apparent in comparison to QuikSCAT  
367 but the scatter of the data is somewhat reduced and, most importantly, a negative correla-  
368 tion versus  $u_p$  is also observed. However, it is also clear that there is a large difference in the  
369 slopes observed for the 12 km and 25 km products ( $-0.53$  and  $-0.51$  for binned slopes), and  
370 that for the Coastal ASCAT product ( $-1.07$  binned slope). Only the coastal products lies  
371 near that observed for the Ku-band QuikSCAT. The correlation coefficient for the coastal  
372 product of  $-0.48$  is also elevated beyond that seen for any other dataset.

373

374 Altimeter-buoy wind residuals versus  $u_p$  are shown in Figs. 11 and 12. As previously  
375 mentioned, only observations at buoy N are used because the passage of altimeter tracks  
376 near to buoy L was much more limited. Recall that this dataset represents a compilation  
377 drawn from the combination of Ku-band sensors aboard the Jason-1, -2, and Envisat plat-  
378 forms. While again the sample population is much lower than for QuikSCAT, these data  
379 show remarkably similar results to that shown for QuikSCAT, for example in Fig. 6. The  
380 weighted least squares fit of Fig. 12 yields a slope of  $-0.97 \pm 0.26$  and the linear correlation  
381 coefficient of 0.204 is near that seen for the scatterometer. These altimeter results are for  
382 the full range of observed surface conditions without filtering for wind regimes or stability  
383 effects, due to the limited number of samples.

384

## 385 4. Discussion

386 The observational evidence to date concerning the treatment of scatterometer ocean wind  
387 as a current-relative velocity lies primarily within five studies (Quilfen et al. (2001), Cornil-  
388 lon and Park (2001), Dickinson et al. (2001), Kelly et al. (2001), Kelly et al. (2005)) with the  
389 former addressing the C-band ERS scatterometer and the remainder Ku-band NSCAT or  
390 QuikSCAT data. In most cases, these studies relate separate long-term averages of currents  
391 and of wind (or wind vector) residuals leading to convincing causal evidence such as Fig.  
392 4 in Cornillon and Park (2001), Fig. 6 in Chelton et al. (2004), and Fig. 3 in Kelly et al.  
393 (2001). However, only Dickinson et al. (2001) provides a quantitative estimate of the trans-  
394 fer function between observed zonal wind differences and the zonal current with their linear  
395 regression coefficient being 1.3 at Ku-band, suggesting enhanced wind perturbation beyond  
396 the 1:1 relationship with  $\mathbf{U}_s$  of Eq. 1. Results from the C-band ERS scatterometer seen in  
397 Fig. 10 in Quilfen et al. (2001)) indicate a slope possibly exceeding 1.0 but actual linear

398 regression coefficients are not provided. Given the low value of the linear correlation coeffi-  
399 cient and varied noise sources contributing to mask current impacts in all of these studies, it  
400 is understandable that direct and formal quantification has been difficult. Results presented  
401 here for QuikSCAT provide a new and complementary quantification with detailed estimates  
402 of uncertainty as summarized in Fig. 7 and Table 2. The observed relationship between wind  
403 residuals and the effective current in the Gulf of Maine region clearly affirms that the scat-  
404 terometer yields a current-relative wind. Moreover, the data lead us to conclude that for  
405 the Ku-band scatterometer there is no statistical justification to deviate from a slope of 1.0  
406 with the actual best-case isolation for currents yielding a slope of  $-0.96 \pm 0.12$  (for 12 km  
407 data). The large sample population and use of the daily variations in tidal flow contained in  
408 this study seem to allow isolation of the phenomenon, but we do note that much averaging  
409 is required as the circulation dynamics near our buoys L and N (Smith et al. (2003)) are  
410 much more active than within the persistent warm core rings of large-scale currents used in  
411 previous investigations, possibly leading to increased differences due to time-and-space lags.  
412 This is the likely reason for the observed linear correlation coefficients nearer to 0.2 as op-  
413 posed to 0.4 to 0.6 cited earlier. While it is possible that choosing a different scatterometer  
414 solution (ambiguity) rather than the standard “best case” solution (see Sec. 2) might lead to  
415 slightly higher correlations, these results are based on only the most likely choice as given by  
416 the DIRTH algorithm as that is the most commonly used form of scatterometer data product.

417

418 Another possible contribution to low correlations is boundary layer (BL) modification  
419 due to stability. For a two-layer BL model, the inner (surface) layer is logarithmic and cor-  
420 rected for stratification, humidity, and surface roughness (the neutral version of this is given  
421 as Eq. 1), and the outer is a stratification-dependent Ekman layer, associated with rotation  
422 of the wind with height and stability (Businger and Shaw (1984); Brown and Liu (1982)).  
423 At the surface, it is assumed that the stress direction is the same as the wind direction.  
424 But in certain circumstances, the direction of the wind at the height of the anemometer

425 on the buoys (3 m) may have already been affected by stratification, (Businger and Shaw  
426 (1984), Fig. 2), causing it to be different from the direction derived at the surface from the  
427 scatterometer. This turning or rotation could impact the validity of  $u_p$  as defined, and add  
428 noise to the overall results. This would be especially true during stable conditions. However,  
429 given the methods for calibrating the scatterometer GMFs, using the basic surface layer  
430 model and the buoy wind direction without an additional turning angle is sufficient for a  
431 study containing the range of conditions present here (Foster (2012)).

432

433 Results from section 3 also serve to address the question of equal treatment of C-band and  
434 Ku-band scatterometer data as well as that from systems such as the microwave altimeter.  
435 It is understood that the ocean radar backscatter for each sensor is uniquely related to the  
436 transmit frequency, polarization and incidence angle and the interaction of the signal with  
437 the spectrum of waves on the sea surface. However, for these three systems and most passive  
438 and active microwave wind sensors, the fundamental issue of a changing bottom kinematic  
439 boundary condition should lead to a current-relative wind for the cases of large scale currents.  
440 In this study we find this to be the case, where the C-band ASCAT coastal wind product  
441 data, the Ku-band altimeter winds, and QuikSCAT all yield statistically similar results over  
442 the same buoy sites. Knowing the altimeter reflects a broader integration of wave scales in  
443 its backscatter and wind estimates compared to the weighting of scatterometers towards 2-8  
444 cm scale gravity-capillary wave roughness scales (cf. Mouche et al. (2007)), we infer that all  
445 wave scales shorter than roughly 10-20 m are, on average, adjusted to the local wind and  
446 surface current environment. This is also in agreement with recent wave-current interaction  
447 modeling efforts (Kudryavtsev et al. (2012)). One can then expect similar results for lower  
448 frequency radar (e.g. L-band) and for passive microwave systems such as SSM/I, AMSR-E  
449 and Windsat. Results also offer insight into the spatial scale of currents near buoys N and  
450 L in the Gulf of Maine and, in turn, why the upper panel ASCAT data of Figs. 9 and 10  
451 differ from ASCAT coastal product findings. Similar current-relative regression statistics are

452 observed for all three QuikSCAT data products spanning down from 25 to 12 to the nomi-  
453 nally 5 km UHR. This is not the case for the ASCAT data where the relationship between  
454 currents and the wind residuals is largely lost for the 25 and 12 km data. This apparent  
455 difference between ASCAT and QuikSCAT is known to be a consequence of the data pro-  
456 cessing window rather than physics. Once we incorporated the newer coastal product into  
457 the study, it became clear that the shallow slopes obtained using data produced under the  
458 standard spatial Hamming window (of order 50 km at the 3 dB points) used to filter ASCAT  
459 25 and 12 km data resulted in a satellite wind footprint smearing. This is consistent with  
460 the expectation that spatial averaging beyond 25 km would exceed the typical zonal length  
461 scale of currents in the Northeast channel near buoy B as well as northward at buoy L (Chen  
462 et al. (2011)). Future studies using ASCAT data in any buoy-satellite wind comparisons  
463 should closely consider these spatial windowing issues.

464

465 To further discuss the issues related to spatial variability of current interactions in scat-  
466 terometry, a case study was developed to explore the effect across the marginal shelf region  
467 containing the two buoys. For this purpose, hindcast model surface wind data were differ-  
468 enced with scatterometer swath data to examine possible differences in wind field spatial  
469 structures in comparison to expected ocean currents. The weather model data come from  
470 regional multi-resolution (3km, 9km, and 27km) weather research and forecasting (WRF)  
471 model output (Skamarock and Klemp (2008)) produced routinely at UNH. Our chosen prod-  
472 ucts were the 3-hourly 9km domain 10-m wind vectors ( $u$  and  $v$ ) and surface air temperature  
473 fields. The WRF model version was 2.1.2 and the Yonsei University scheme was used to pa-  
474 rameterize the planetary boundary layer (Hong et al. (2006)). No ocean currents were used in  
475 the bottom boundary condition for WRF model runs and only climatological SST data were  
476 used. For diagnosing wind residuals, hourly hindcast oceanic surface current vectors were  
477 used from the Gulf of Maine Finite Volume Community Ocean Model (FVCOM) circulation  
478 model developed by Dr. Chen and colleagues the University of Massachusetts. Because it

479 uses an unstructured grid, FVCOM's fields have no fixed resolution, but this output had  
480 spacing below 5 km at all nodes in our region of interest. For these data as well as the  
481 12.5 km QuikSCAT retrievals, linear interpolation was used to resample all data to 9 km for  
482 comparison with the atmospheric model.

483

484 Fig. 13 presents one case of wind, current, and wind residual estimates from a 2-degree-  
485 by-2-degree area of the Gulf of Maine that includes Buoy L and N and represents a region  
486 of strong M2 tidal flow. Note that Fig. 1 provides a full regional map and the location  
487 of this region of interest. This specific case occurred near to 00UTC 27 Dec. 2008 and is  
488 chosen to illustrate one extreme case of current impacts upon scatterometer winds. Here  
489 the ocean model (2258UTC 26 Dec. 2008, see panel a) indicates flood tide conditions with  
490 the currents greater than  $50 \text{ cm s}^{-1}$  generally directed to the NNW and with enhanced flow  
491 near to Nova Scotia (43.3N) and also in the center near Brown's Bank (closed bathymetric  
492 contour near 42.5N, 66.2W). QuikSCAT winds (2312UTC, Dec. 26 2008, see panel c) are  
493 from the NNW nearly in opposition to the tidal flow. This December case was also cho-  
494 sen for uniformity in the sea surface temperature fields (not shown) to limit non-current  
495 impacts due to marine boundary layer and SST front features. Fig. 13b WRF-predicted  
496 winds (00UTC Dec. 27 2008) indicate a much smoother spatial field than for QuikSCAT  
497 but similar NNW direction. The average WRF wind speed within this ROI was  $2.41 \text{ m}$   
498  $\text{s}^{-1}$  below QuikScat, a number significantly in excess of the mean current ( $0.4 \text{ m s}^{-1}$ ). We  
499 therefore create the wind residual between QuikSCAT and WRF to take into account the  
500 mean wind speed offset and the mean current offset, and arrive at the wind difference map  
501 of Fig. 13d. Note that the WRF data are for 00UTC and the scatterometer data are taken  
502 one hour before, yet it is the spatial variation of the residuals (seen in panel d) that is most  
503 important here along with its relationship to the ocean currents given in Fig. 13a. The  
504 wind residual map indicates a clear enhancement of the scatterometer winds in Fig. 13d  
505 near to the coast of Nova Scotia and then periodic enhancement towards the SSW across to

506 Georges Bank in the very SW corner of the image. These features are qualitatively similar  
507 to the dynamics of the FVCOM currents in Fig. 13a. While illustrative, we found it difficult  
508 to use this WRF-FVCOM-QuikSCAT approach to rigorously examine current effects in this  
509 region. This is likely because of the combined issues of time and space variability of the wind  
510 and currents, temporal differences between model and satellite products, and model inac-  
511 curacies. The work performed using long-term averaging of scatterometer wind anomalies  
512 in large scale and persistent currents (Chelton et al. (2004), Kelly et al. (2005), Park et al.  
513 (2006)) have shown better results in that respect. However, as known from SAR studies,  
514 the instantaneous signature of wave-current interactions are likely to exist at the surface in  
515 terms of roughness features, but may be difficult to isolate in scatterometer wind products  
516 due in part to the inherent 10-25 km spatial resolution. Results from a recent SAR study in  
517 strong tidal currents (Hansen et al. (2012)) may serve to illustrate this point. In their case,  
518 a scene with similar tidal magnitudes and scales is viewed in the coastal Norwegian Sea.  
519 As expected, SAR radar cross section imagery (see their Fig. 5) delineate current impacted  
520 regions at significantly finer scale than found in our Fig. 13.

521

## 522 5. Conclusions

523 This study has used *in situ* mooring data and measurements of the tidally dominated  
524 currents in the Gulf of Maine to show that satellite winds derived from Ku-band scatterom-  
525 etry, C-band scatterometry, and Ku-band altimetry all provide a current-relative, rather  
526 than earth-relative, wind speed. We are able to quantify this conclusion by finding slopes  
527 between buoy and satellite wind residuals and the wind-projected currents that lie at -  
528  $0.96\pm 0.12$ ,  $-1.07\pm 0.37$ , and  $-0.97\pm 0.26$ , for best-case 12 km QuikSCAT, coastal ASCAT,  
529 and a complement of altimeters respectively. While the expectation and demonstration of  
530 ocean current effects upon scatterometer winds is not new, this study significantly advances

531 quantitative certainty in the current-relative wind assumption made within Eq. 1, and in  
532 its application to winds derived both from satellite sensors that primarily respond to short-  
533 scale Bragg waves and those responding to a broader spectrum such as the altimeter and  
534 radiometer.

535

536 On the whole, this study affirms that for surface currents with length scales of 10 km and  
537 longer, microwave remote sensing winds can be considered to be current-relative; a result that  
538 is consistent with *in situ* and satellite scatterometer comparisons in large equatorial currents  
539 (Dickinson et al. (2001), Quilfen et al. (2001)). The difference between earth-relative and  
540 current-relative wind can be quite pronounced across this coastal site where current magni-  
541 tudes of 10-20% of the wind velocity are quite common, and the impact on the pseudostress  
542 would be even higher. In fact, the region's reversing M2 tide must be driving a measurable  
543 semi-diurnal difference in the wind stress over a fairly large portion of the eastern Gulf of  
544 Maine for those cases when the synoptic winds near alignment with the tidal ellipse. Typical  
545 twice-daily sampling by scatterometry is unlikely to fully capture this feature, but predictive  
546 regional atmosphere-ocean modeling should consider this impact (cf. Kara et al. (2007)).  
547 As discussed elsewhere (Chelton et al. (2004), Park et al. (2006)), the present results also  
548 predict that wind stress curl fields computed from scatterometer data in this region will, at  
549 times, show spatial structure that is closely related to the tidal flow and its interactions with  
550 bathymetry in the Gulf of Maine. Based on the similar findings of current impacts for the  
551 altimeter and scatterometer, it is expected that when the spatial scale of the currents and  
552 thus the kinematic boundary condition is large enough, even the 50 km footprint of scanning  
553 microwave radiometers will provide current-relative winds; this has significant implications  
554 for developing accurate long-term climate records that merge satellite wind speed and wind  
555 vector data.

556

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## 692 List of Tables

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- 696 2 Statistics from the same weighted least squares fit of wind residuals versus  
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698 tions. Significant wave height and the Monin-Obukov stability length scale  
699 parameter ( $L$ ) come from buoy observations; stability of boundary layer is  
700 based on definitions in Large and Pond (1982). Results are for combined  
701 buoy L and N datasets. 30

	<b>Resolution</b>	<b>Slope</b>	<b>Slope SD</b>	<b>Y-Inter.</b>	<b>Y-Inter. SD</b>	<b>Corr.</b>	<b>N</b>
Buoy L	UHR	-0.83	0.10	-0.23	0.03	-0.201	1615
	12 km	-0.87	0.10	-0.04	0.04	-0.195	1282
	25 km	-0.86	0.13	0.00	0.05	-0.195	847
Buoy N	UHR	-0.87	0.09	-0.15	0.03	-0.175	2015
	12 km	-0.84	0.09	+0.03	0.03	-0.143	1972
	25 km	-0.81	0.13	0.00	0.05	-0.146	1017
Buoys L and N	UHR	-0.85	0.07	-0.18	0.02	-0.185	3627
	12 km	-0.82	0.07	+0.01	0.03	-0.161	3250
	25 km	-0.92	0.10	+0.01	0.03	-0.166	1862

Table 1: Slopes, intercepts, and their uncertainties for the weighted least squares fit of wind speed residuals ( $\text{m s}^{-1}$ ) versus  $u_p$  for different QuikSCAT resolutions and for different buoys.

Regime/Rule	Res.	Slope	Slope SD	Y-Int.	Y-Int. SD	Corr.
<i>buoy wind speed</i> $\leq 5$	UHR	-0.82	0.10	-0.14	0.03	-0.192
	12.5 km	-0.86	0.11	+0.06	0.04	-0.167
	25 km	-1.00	0.15	-0.01	0.05	-0.161
$5 < \textit{buoy wind speed} \leq 10$	UHR	-0.95	0.09	-0.41	0.03	-0.206
	12.5 km	-0.98	0.09	-0.21	0.03	-0.213
	25 km	-1.01	0.13	-0.21	0.04	-0.204
<i>buoy wind speed</i> $> 10$	UHR	-1.05	0.18	+0.28	0.05	-0.193
	12.5 km	-0.94	0.22	+0.42	0.07	-0.112
	25 km	-1.07	0.25	+0.51	0.09	-0.173
<i>sig. wave height</i> $\leq 1$	UHR	-0.96	0.12	-0.44	0.04	-0.198
	12.5 km	-0.94	0.11	-0.27	0.04	-0.238
	25 km	-1.01	0.14	-0.34	0.05	-0.223
$1 < \textit{sig. wave height} \leq 1.6$	UHR	-1.17	0.14	-0.28	0.05	-0.262
	12.5 km	-1.24	0.12	-0.11	0.05	-0.295
	25 km	-1.28	0.17	-0.11	0.06	-0.268
<i>sig. wave height</i> $> 1.6$	UHR	-0.82	0.12	+0.17	0.04	-0.160
	12.5 km	-0.86	0.12	+0.35	0.04	-0.166
	25 km	-0.84	0.18	+0.41	0.06	-0.132
$-0.4 \leq z/L \leq 0.1$ (near-neutral)	UHR	-0.86	0.09	-0.06	0.03	-0.210
	12.5 km	-0.90	0.10	+0.11	0.04	-0.18
	25 km	-0.79	0.13	+0.07	0.05	-0.194
$z/L > 0.1$ (stable)	UHR	-1.00	0.10	-0.61	0.04	-0.196
	12.5 km	-0.95	0.10	-0.41	0.04	-0.168
	25 km	-0.94	0.15	-0.35	0.05	-0.149
$z/L < -0.4$ (unstable)	UHR	-0.70	0.22	+0.57	0.06	-0.131
	12.5 km	-0.72	0.23	+0.67	0.07	-0.098
	25 km	-0.55	0.35	+0.57	0.10	-0.127
Best: mod. wind, near-neut.	UHR	-0.93	0.11	-0.25	0.04	-0.250
	12.5 km	-0.96	0.12	0.11	0.04	-0.256
	25 km	-1.00	0.17	-0.16	0.06	-0.266
Worst: light wind, unstable	UHR	-0.52	0.28	+0.66	0.08	-0.122
	12.5 km	-0.55	0.29	+0.78	0.09	-0.071
	25 km	-0.31	0.46	+0.69	0.13	-0.116

Table 2: Statistics from the same weighted least squares fit of wind residuals versus currents as for Table 1 but after filtering for different air-sea interface conditions. Significant wave height and the Monin-Obukov stability length scale parameter ( $L$ ) come from buoy observations; stability of boundary layer is based on definitions in Large and Pond (1982). Results are for combined buoy L and N datasets.

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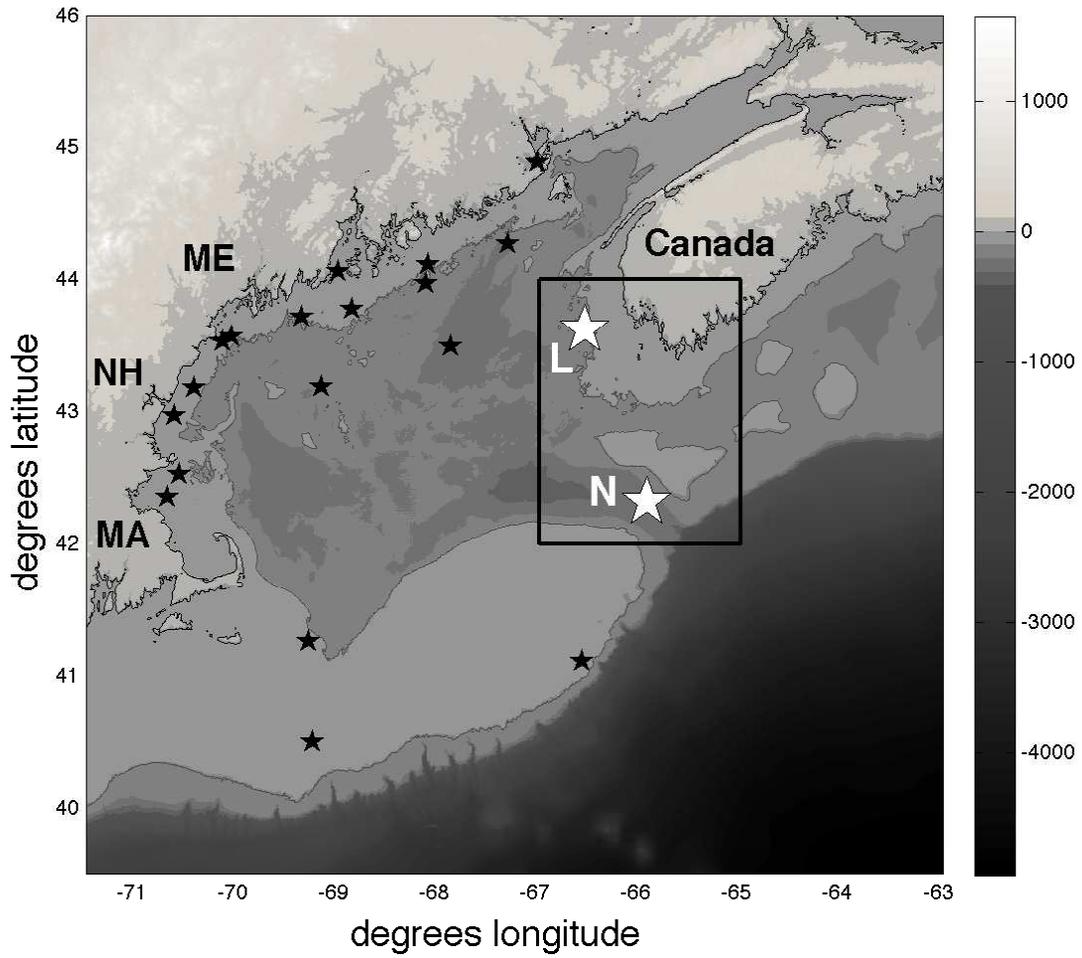


Figure 1: Map of the Gulf of Maine region in the northeast US and Canada including bathymetry and with the inset showing the study site. Star symbols indicate regional observing system buoys (black) with this study's surface current and wind measurement time series nodes, buoys N and L, shown in white.

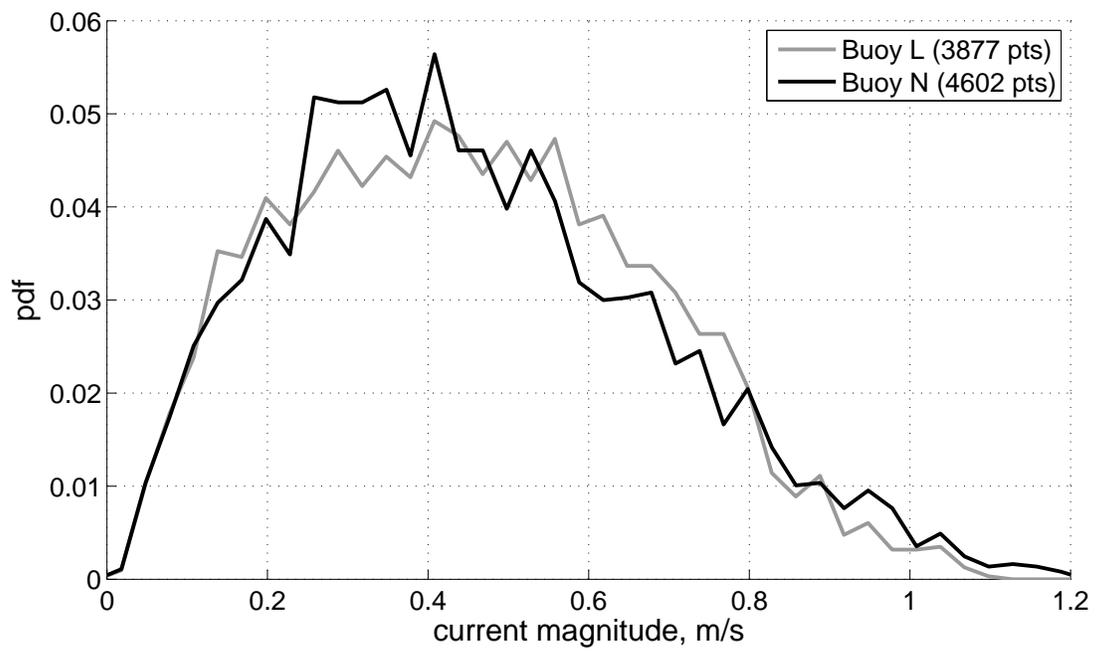


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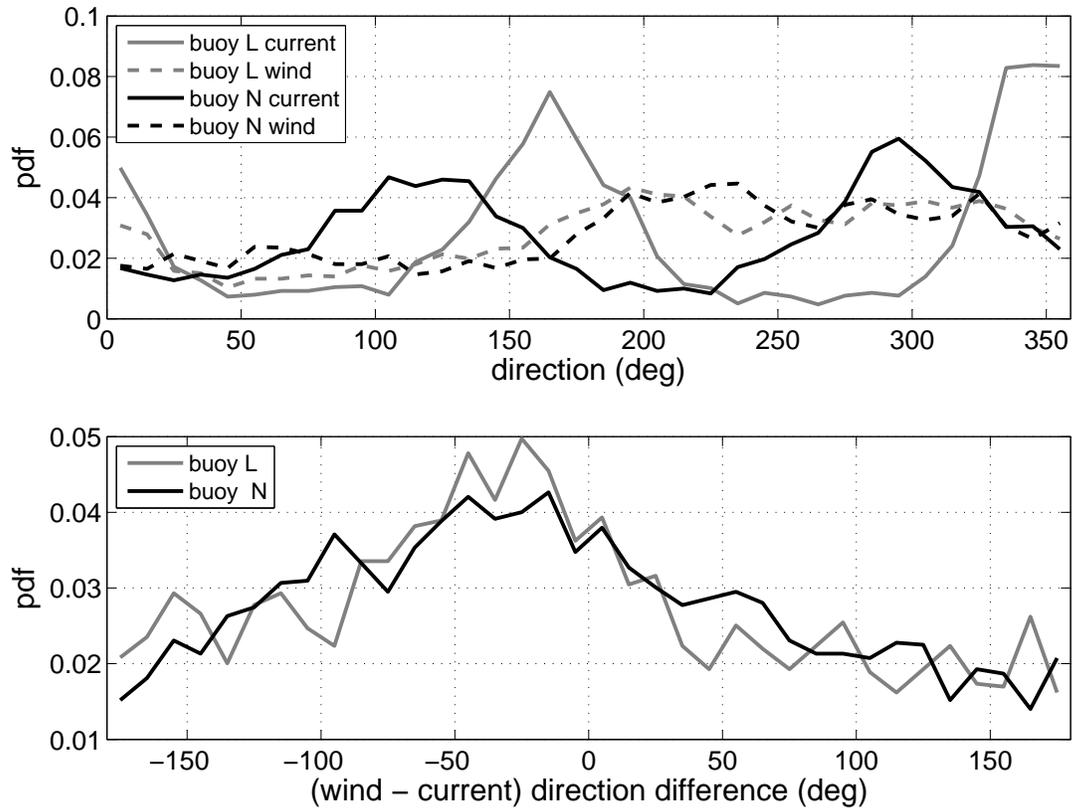


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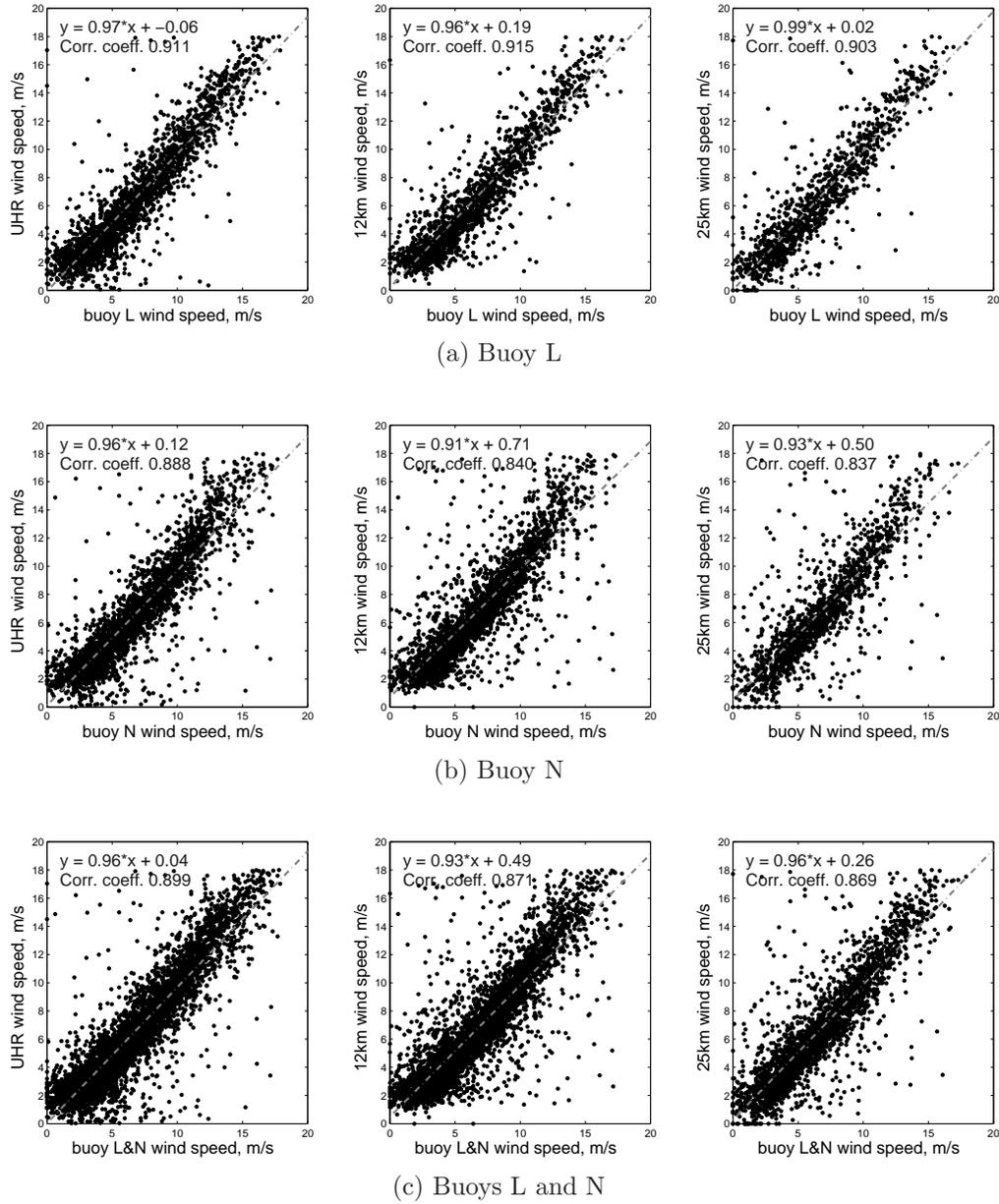


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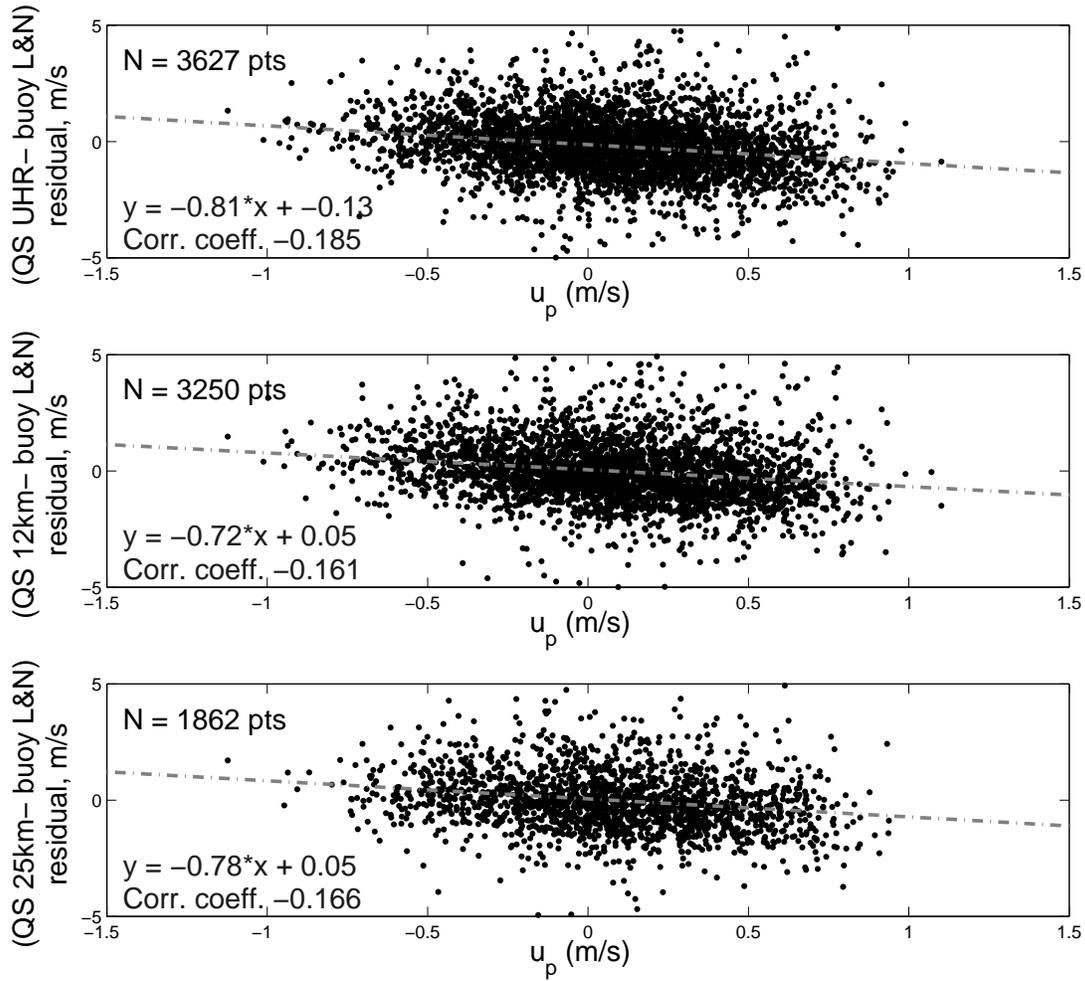


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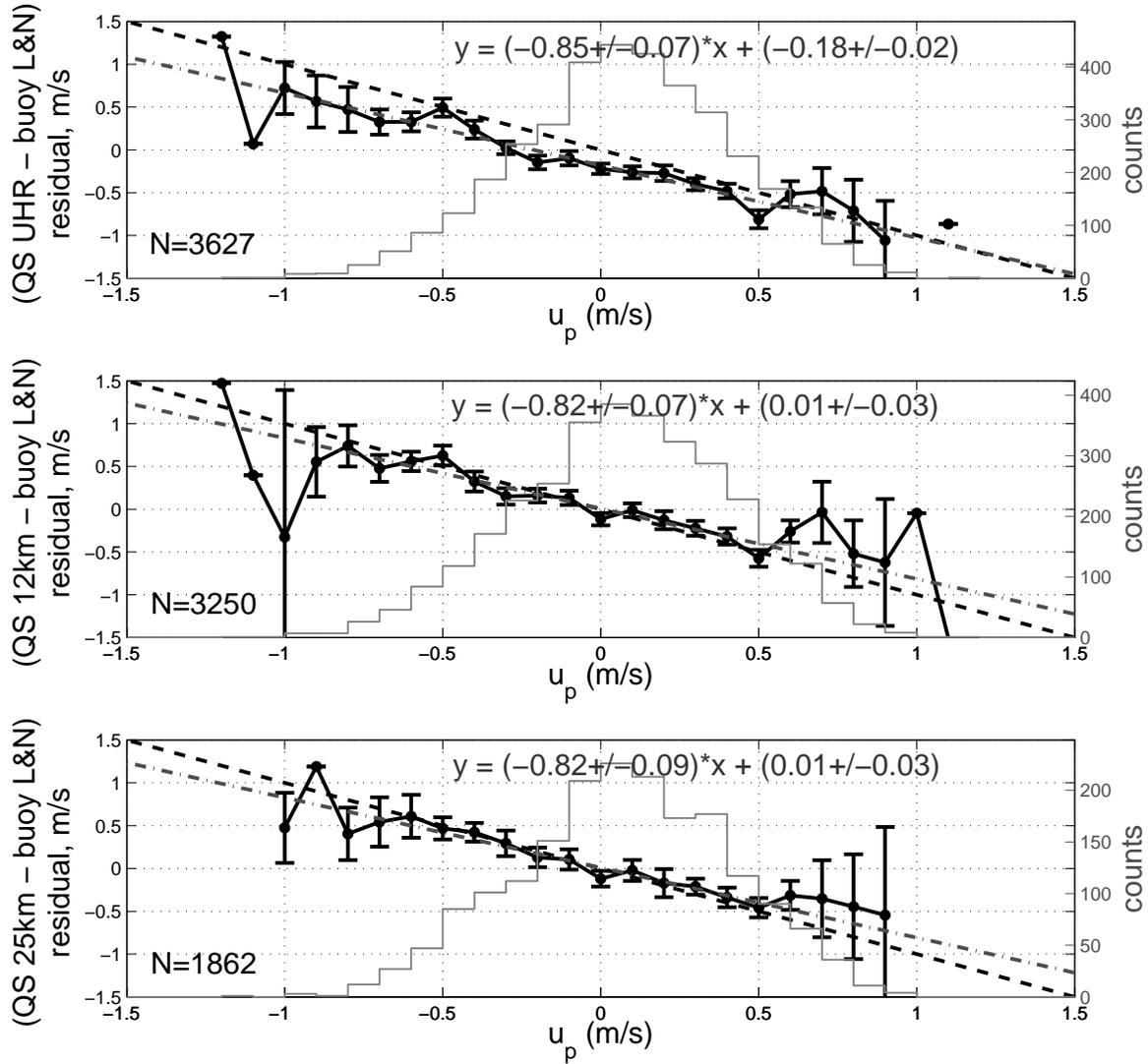


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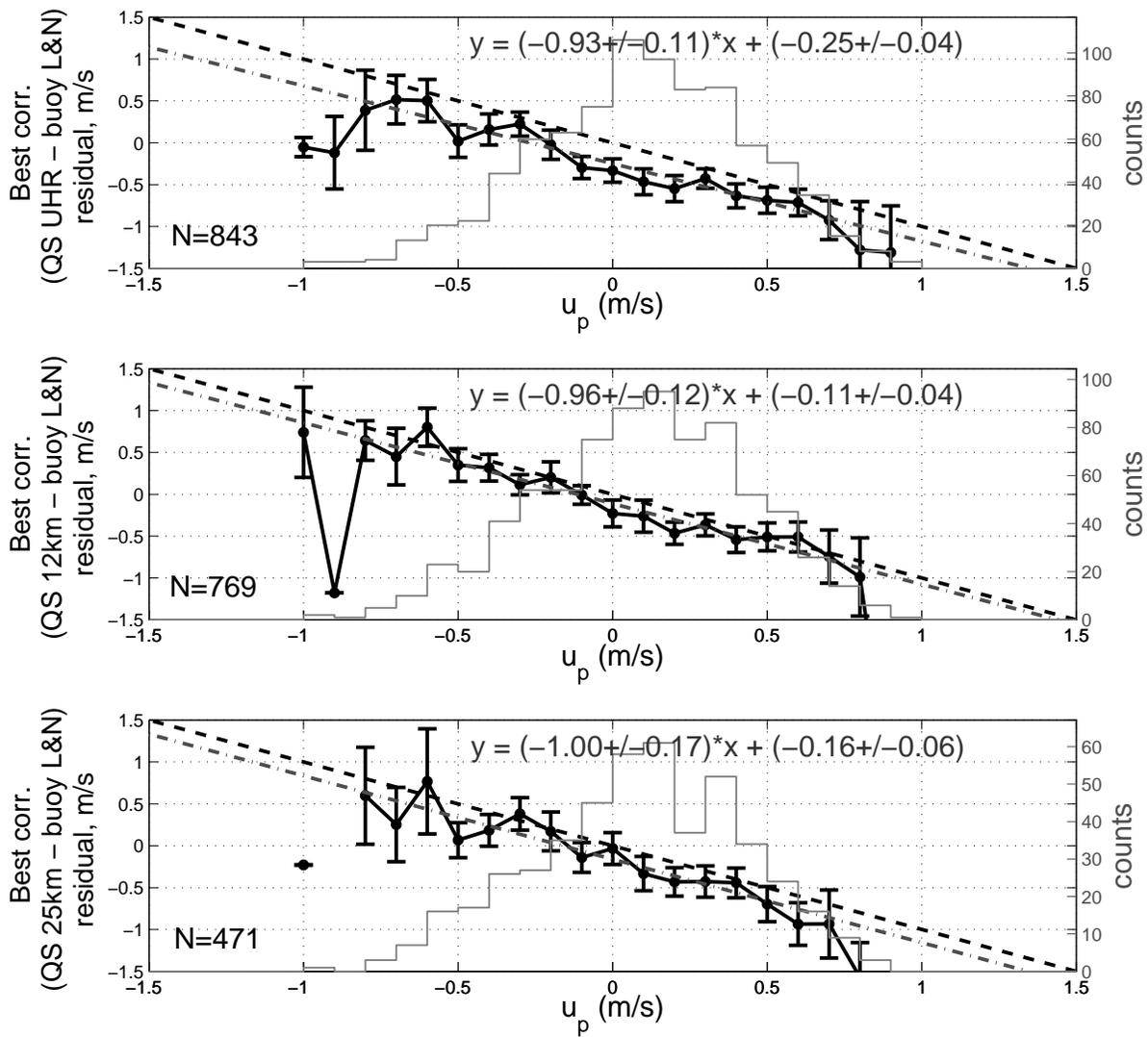


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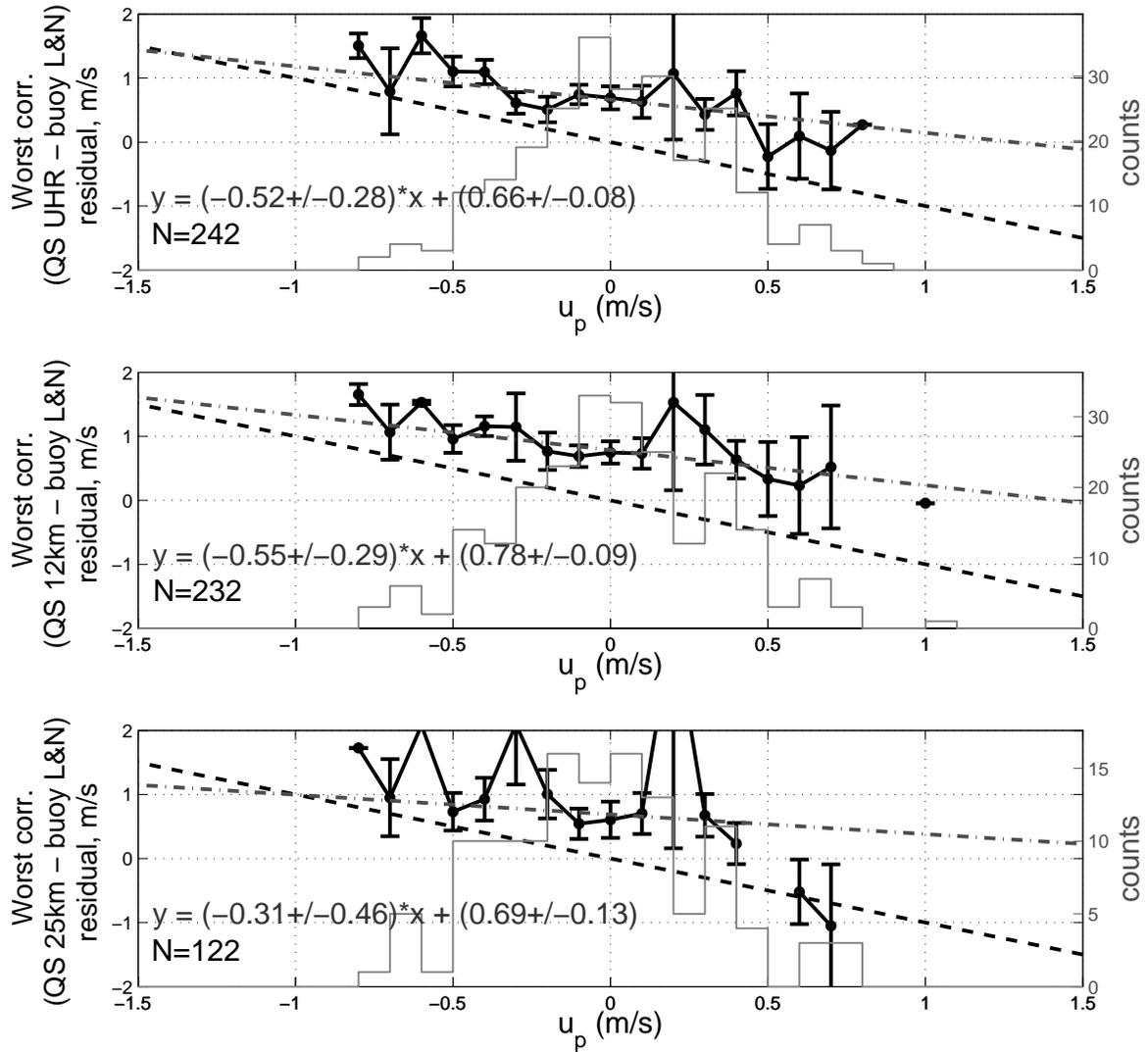


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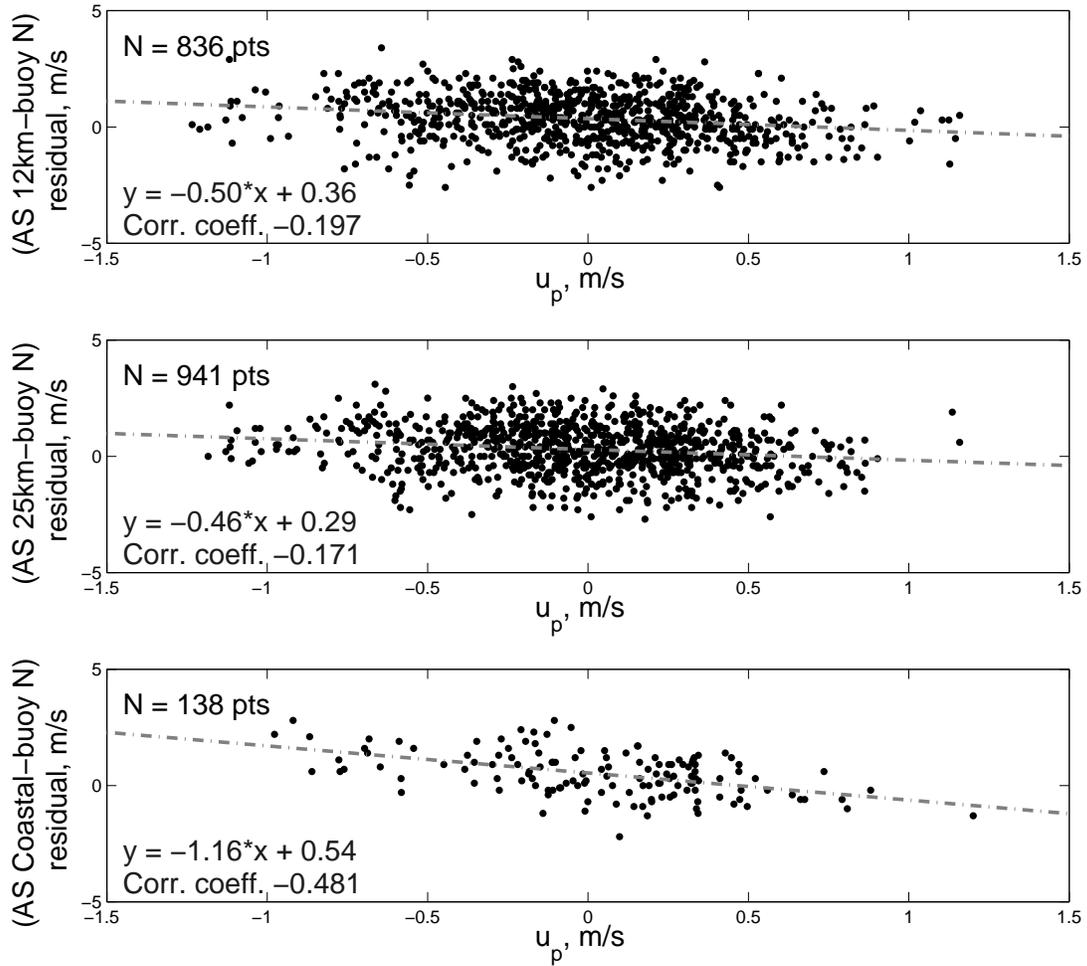


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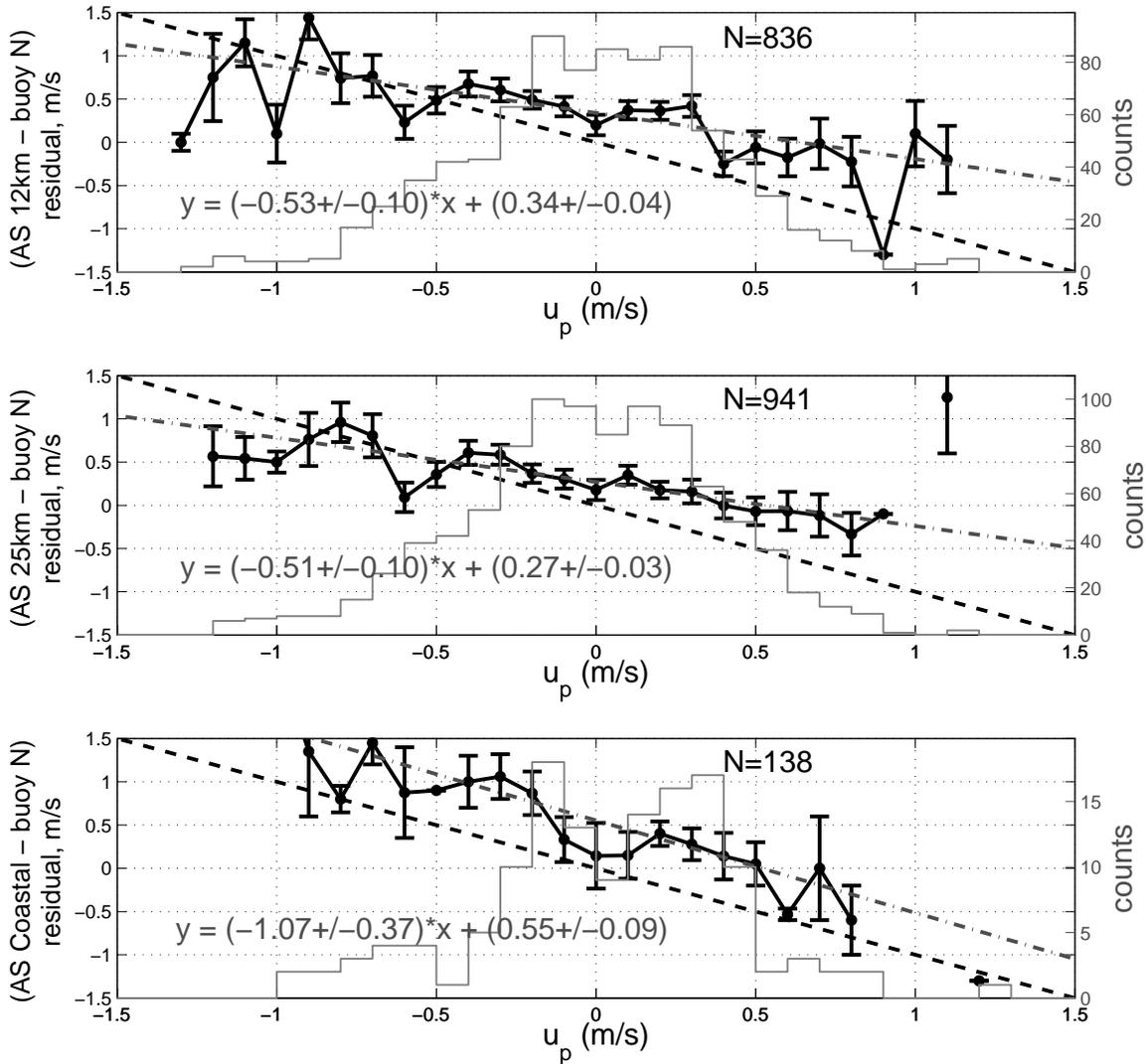


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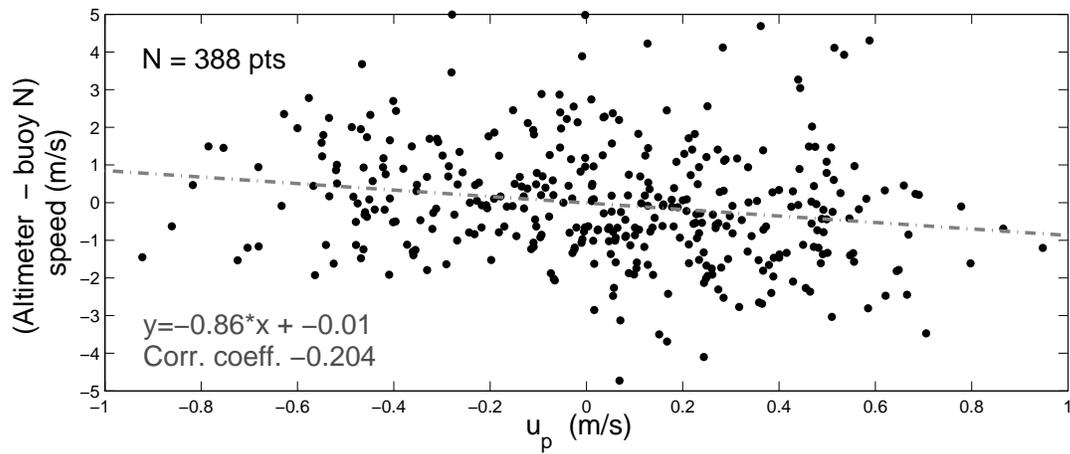


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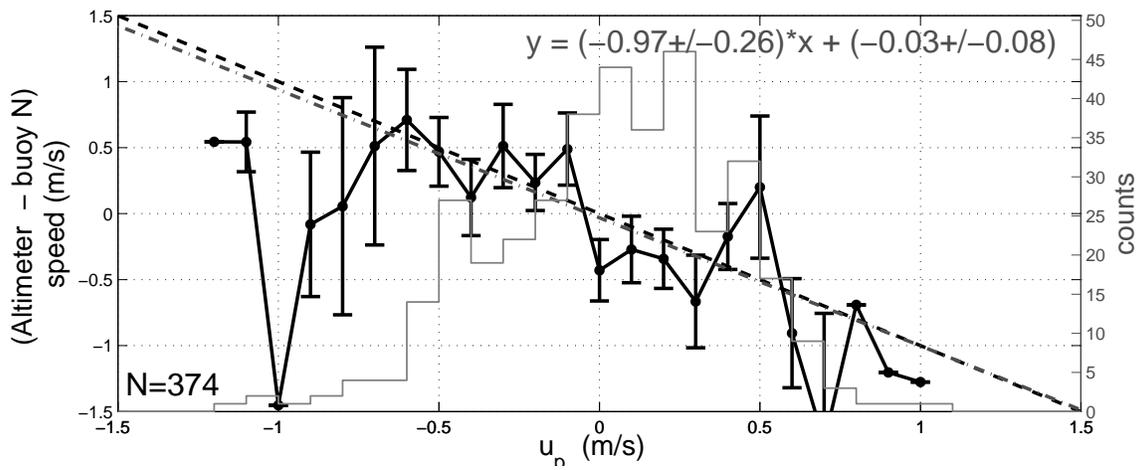


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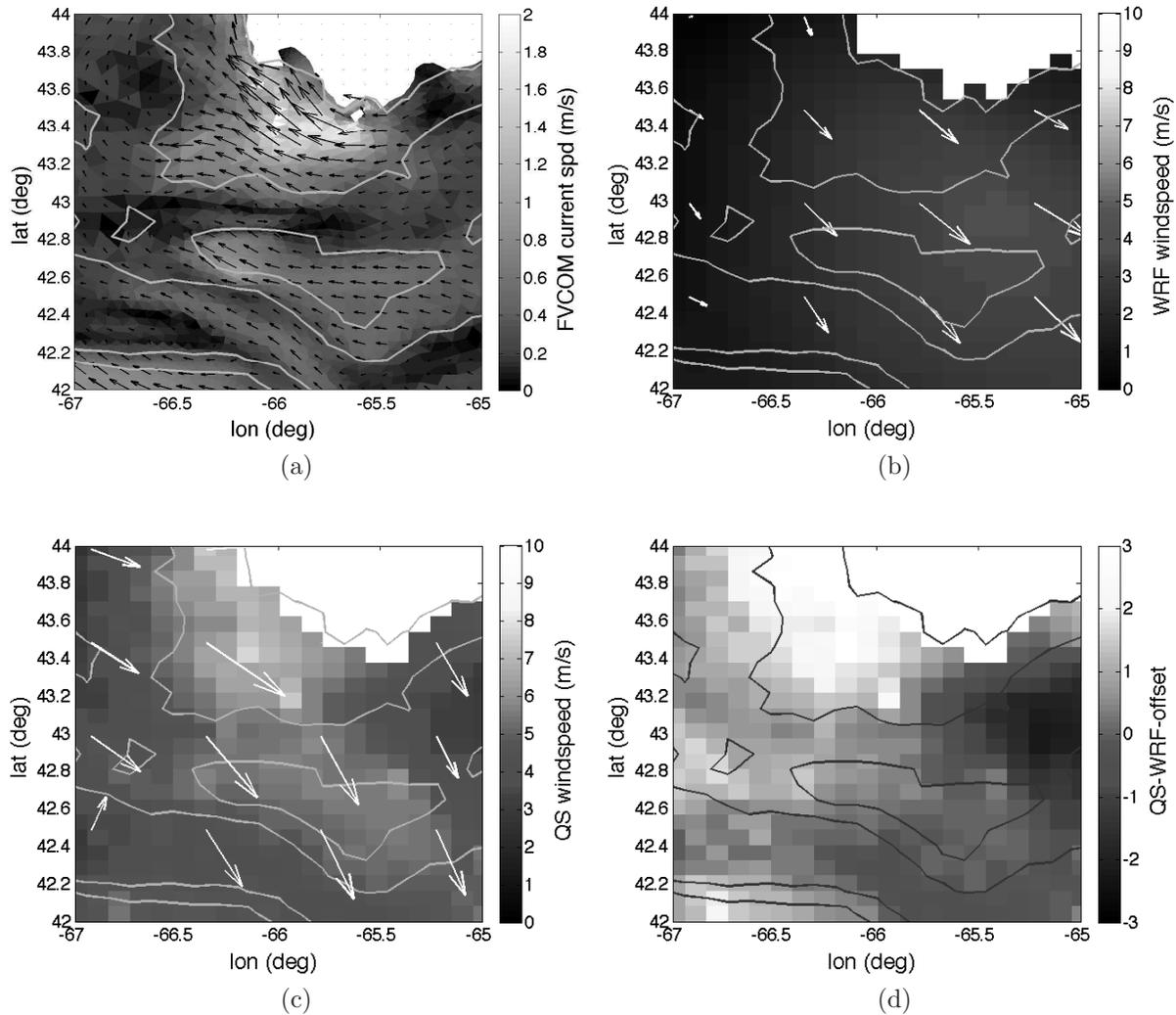


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